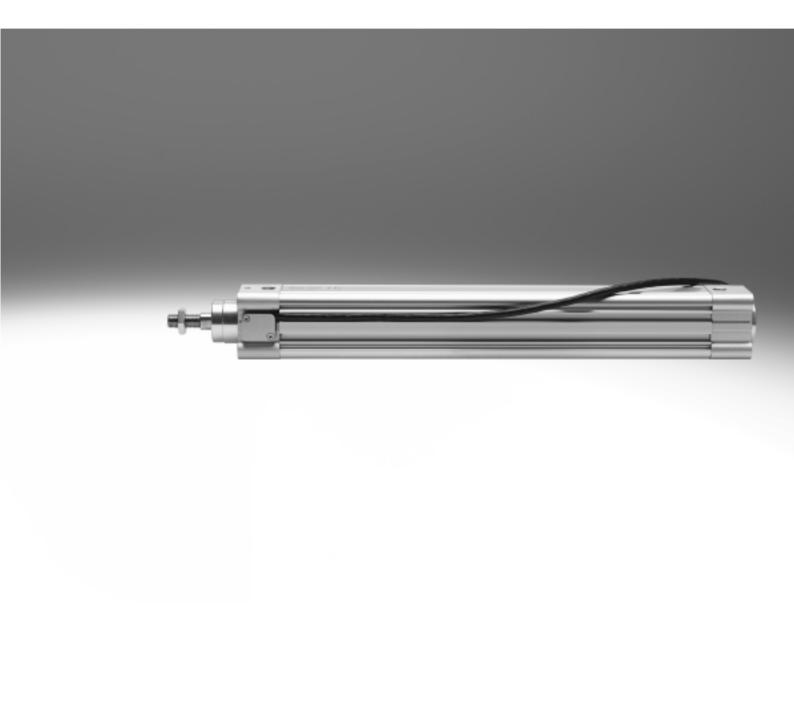
# **FESTO**



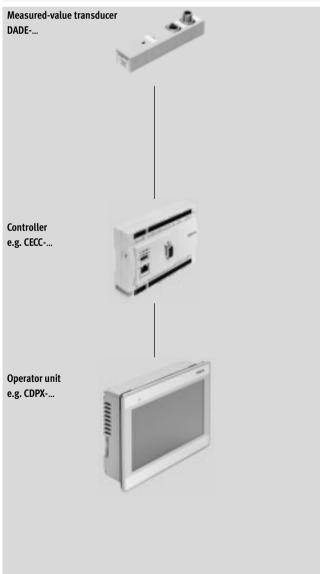


#### Components for positioning and measuring using the standard cylinder DNCI



## Measuring

## with measured-value transducer DADE



Positioning with end-position controller SPC11 or controller module CPX-CMAX/-CMPX

control valve MPYE-...

Proportional directional





**End-position controller** 

Proportional directional control valve VPWP-...



Sensor interface CASM-S-D3-R7



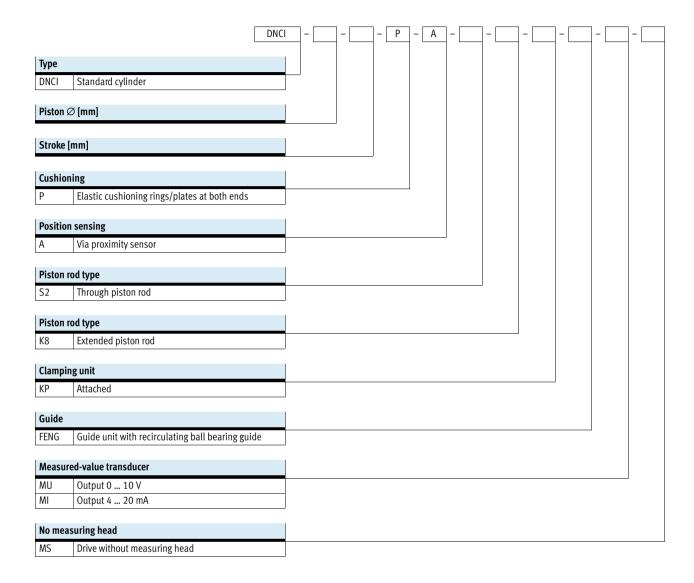
Controller module CPX-CMAX, CPX-CMPX





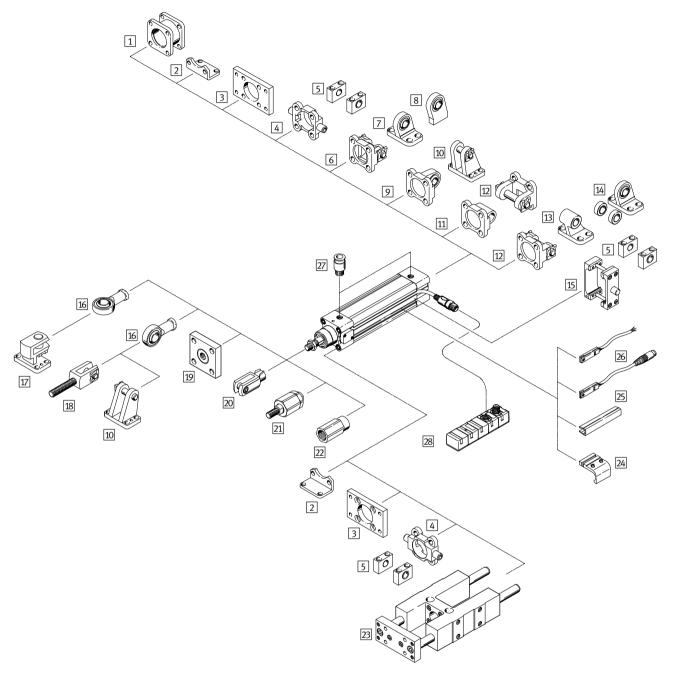
3

Type codes



# Standard cylinders DNCI, with measured-value transducer DADE Peripherals overview





Acce	Accessories									
	Туре	Description	→ Page/Internet							
1	Adapter kit <sup>1)</sup> DPNC	For connecting two cylinders with identical piston $\varnothing$ to form a multi-position cylinder	dpnc							
2	Foot mounting HNC	For mounting the drive on the bearing and end caps	hnc							
3	Flange mounting FNC	For mounting the drive on the bearing and end caps	fnc							
4	Trunnion flange ZNCF/CRZNG	For swivelling movements of the drive on the bearing or end caps	trunnion flange							
5	Trunnion support LNZG/CRLNZG	-	lnzg							

# Standard cylinders DNCI, with measured-value transducer DADE Peripherals overview



Acce	ssories		
	Туре	Description	→ Page/Internet
6	Swivel flange <sup>1)</sup>	For swivelling movements of the drive on the end cap	snc
_	SNC		
7	Clevis foot mounting <sup>1)</sup>	With spherical bearing	lsng
	LSNG		
8	Clevis foot mounting <sup>1)</sup>	Weld-on, with spherical bearing	lsnsg
	LSNSG		
9	Swivel flange <sup>1)</sup>	For swivelling movements of the drive on the end cap, with spherical bearing	sncs
	SNCS		
10	Clevis foot mounting <sup>1)</sup>	-	lbg
	LBG		
11	Swivel flange <sup>1)</sup>	For swivelling movements of the drive on the end cap	sncl
	SNCL		
12	Swivel flange <sup>1)</sup>	For swivelling movements of the drive on the end cap	sncb
	SNCB		
13	Clevis foot mounting <sup>1)</sup>	-	Ing
	LNG/CRLNG		
14	Clevis foot mounting <sup>1)</sup>	With spherical bearing	lsn
	LSN		
15	Trunnion mounting kit	For swivelling movements of the drive	damt
	DAMT		
16	Rod eye	With spherical bearing	sgs
[7=]	SGS/CRSGS		1
17	Right-angle clevis foot	-	lqg
40	LQG Rod clevis	With male thread	
18	SGA	with mate thread	sga
19	Coupling piece	To compensate for radial deviations	ksg
[19]	KSG	To compensate for radial deviations	KSg
	Coupling piece	For cylinders with a non-rotating piston rod to compensate for radial deviations	ksz
	KSZ	Tor cylinders with a non-rotating piston rou to compensate for radial deviations	K3Z
20	Rod clevis	Permits a swivelling movement of the cylinder in one plane	sg
20	SG/CRSG	Termits a switching movement of the cymider in one plane	35
21	Self-aligning rod coupler	For compensating radial and angular misalignments	fk
	FK	To compensating radiat and angular misalignments	
22	Adapter	For a suction cup with connection attachments	ad
	AD		
23	Guide unit	For protecting standard cylinders against rotation at high torque loads	12
	FENG	, , , , , , , , , , , , , , , , , , , ,	
24	Mounting kit	For mounting proximity sensors SME/SMT-8 in combination with guide unit FENG	smb-8-feng
	SMB-8-FENG		
25	Slot cover	For protecting the sensor cable and keeping dirt out of the sensor slots	abp
_	ABP-5-S		
26	Proximity sensor	Can be integrated in the cylinder profile barrel	proximity sensor
	SME/SMT-8		
27	Push-in fitting	For connecting outer toleranced compressed air tubing	qs
	QS		
28	Measured-value transducer	Converts sensor signals of the standard cylinder DNCI into a voltage signal of 0 10 V and/or	16
	MU, MI	a current signal of 4 20 mA	

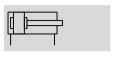
Not with variant S2
 Guide unit FENG-KF must be attached to the piston rod in a way that eliminates backlash

- www.festo.com



Technical data

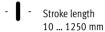
Function







32 ... 63 mm





General Technical data								
Piston ∅		32	40	50	63			
Based on standard		ISO 15552						
Design		Piston						
		Piston rod						
		Profile barrel						
Mode of operation		Double-acting						
Guide <sup>1)</sup>		Guide rod with yoke, v	vith ball bearing gui	ide				
Mounting position		Any						
Type of mounting		Via accessories						
Cushioning		Elastic cushioning rings/plates at both ends						
Position sensing		Integrated displacement encoder						
		Via proximity sensor <sup>2)</sup>						
Measuring principle (displacement encoder)	)	Encoder, contactless a	Encoder, contactless and relative measurement					
Pneumatic connection		G1/8	G1/4	G1/4	G3/8			
Stroke			·	<u>.</u>				
DNCI <sup>3)</sup> [mm]		10 1250						
DNCIFENG	100 500							
Extended piston rod	[mm]	1 500	1 500					

- 1) Guide unit FENG-KF can be ordered via the modular product system (feature FENG) and is supplied attached. The maximum stroke is restricted.
- 2) Not included in the scope of delivery, can be ordered as an option
- Can only be used without restriction as a positioning drive in the range from 100 ... 750 mm.
   Note stroke reduction in combination with CPX-CMAX

Operating and environmental conditions							
Operating pressure [bar]	0.6 12						
Operating pressure <sup>1)</sup> [bar]	48						
Operating medium <sup>2)</sup>	Compressed air to ISO 8573-1:2010 [6:4:4]						
Note on operating/pilot medium	Lubricated operation not possible						
	Pressure dew point 10°C below ambient/medium temperature						
Ambient temperature <sup>3)</sup> [°C]	-20 +80						
Vibration resistance to DIN/IEC 68, Part 2-6	Severity level 2						
Continuous shock resistance to DIN/IEC 68, Part 2-82	Severity level 2						
CE marking (see declaration of conformity) <sup>4)</sup>	To EU EMC Directive						
Corrosion resistance class CRC <sup>5)</sup>	1						

- 1) Only applies to applications with end-position controller CPX-CMPX, SPC11 and axis controller CPX-CMAX
- 2) The proportional directional control valve VPWP, MPYE requires these characteristic values
- Note operating range of proximity sensors
- For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com/sp → Certificates.
- If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.
- 5) Corrosion resistance class 1 according to Festo standard 940 070
- Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers.



Technical data

Maximum permissible load:

Forces [N] and impact energy [Nm]										
Piston ∅	32	40	50	63						
Theoretical force at 6 bar		483	754	1178	1870					
Advancing	S2	415	633	990	1682					
Theoretical force at 6 bar		415	633	990	1682					
Retracting S		415	633	990	1682					
Impact energy at the end positions		0.1	0.2	0.2	0.5					

Permissible impact velocity:  $v_{perm.} = \sqrt{\frac{2 \times E_{perm.}}{m_{latringle} + m_{loc}}}$ 

v<sub>perm.</sub> Permissible impact velocity E<sub>perm.</sub> Maximum impact energy m<sub>Intrinsic</sub> Moving mass (drive)

m<sub>Load</sub> Moving payload

 $v_{perm.} = \sqrt{\frac{m_{Intrinsic} + m_{Load}}{m_{Intrinsic}}}$ 

 $m_{Load} = \frac{2 \times E_{perm.}}{V^2} - m_{Intrinsic}$ 

- Note

These specifications represent the maximum values that can be achieved. Note the maximum permissible impact energy.

Electrical data – displacement encoder		
Output signal		Analogue
Linearity error		
Strokes up to 500 mm	[mm]	< ±0.08
Strokes up to 1000 mm	[mm]	< ±0.09
Strokes over 1000 mm	[mm]	< ±0.11
Resolution <sup>1)</sup>	[%]	≤ 0.025
Repetition accuracy		
≤ 400	[mm]	±0.1
≤ 500	[mm]	±0.13
≤ 750	[mm]	±0.19
≤ 1200	[mm]	±0.3
≤ 1250	[mm]	±0.4
Max. travel speed	[m/s]	1.5
Degree of protection		IP65
CE marking (see declaration of conformity)		To EU EMC Directive <sup>2)</sup>
Maximum permitted magnetic interference	[kA/m]	10
field <sup>3)</sup>		
Electrical connection		Cable with 8-pin plug, round design, M12
Cable length	[m]	1.5

- 1) Always refers to max. Stroke
- 2) For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com/sp > Certificates.

  If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.
- 3) At a distance of 100 mm

#### Pin allocation for plug



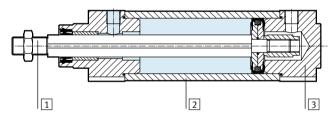
Pin	Function	Colour
1	5V	Black
2	GND	Brown
3	sin+	Red
4	sin-	Orange
5	cos-	Green
6	COS+	Yellow
7	Screened	Screened
8	n.c.	-



Weight [g]					
Piston $\varnothing$		32	40	50	63
DNCI		<b>'</b>			
	Product weight with 0 mm stroke	521	853	1319	1914
	Additional weight per 10 mm stroke	30	44	62	71
	Moving load with 0 mm stroke	95	175	316	383
	Additional weight per 10 mm stroke	8	14	23	23
DNCIS2 - t	hrough piston rod				
5.1.C. III 02 C	Product weight with 0 mm stroke	586	981	1553	2165
	Additional weight per 10 mm stroke	39	60	87	96
	Moving mass with 0 mm stroke	155	164	297	364
	Additional weight per 10 mm stroke	17	30	48	48
DNCIK8 – a	dditional weight with piston rod extension				
	Additional weight per 10 mm stroke	8	14	23	23
DNCIKP – a	dditional weight with clamping unit				
	Product weight	234	394	700	1147
DNCIFENG	– additional weight with guide unit				
	Product weight with 0 mm stroke	1530	2370	4030	5410
	Additional weight per 10 mm stroke	18	32	50	62

#### Materials

Sectional view



Stan	Standard cylinder							
1	Piston rod	High-alloy steel						
2	Cylinder barrel	Anodised aluminum						
3	Bearing/end caps	Die-cast aluminum						
-	Dynamic seals	Polyurethane TPE-U						
-	Static seals	NBR						
	Note on materials	RoHS-compliant						
Disp	lacement encoder							
-	Sensor housing	Polyacetal						
-	Cable sheath	Polyurethane						
-	Plug housing	Polybutylene terephthalate						
_	Mounting plate	Polyacetal						
-	Screws for mounting plate	Steel						

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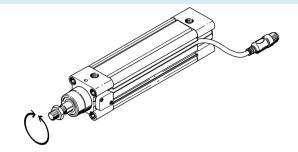
Technical data

#### Torques and lateral forces

The piston rod must not absorb any torque. We therefore recommend using an external guide unit FENG-KF with the drive DNCI. The guide unit is supplied attached.

The permissible static and dynamic characteristic load values with and without attached guide as well as with regard to the technical data of the variants (S2, S8, S9)

→ Internet: dnc



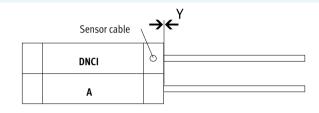
#### **Mounting conditions**

The following conditions must be observed, when mounting a drive A with magnet (for position sensing) next to a standard cylinder DNCI:

- X Minimum distance between the drives
- Y Offset between the drives on the bearing cap

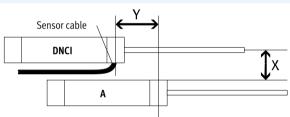
#### Parallel assembly

The drives can be assembled directly next to one another if the offset Y = 0 mm.



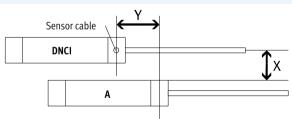
#### Off-set assembly, cable outlet between the drives

A distance of X > 70 mm must be observed, if the offset is Y > 0 mm and the cable outlet is between the drives.



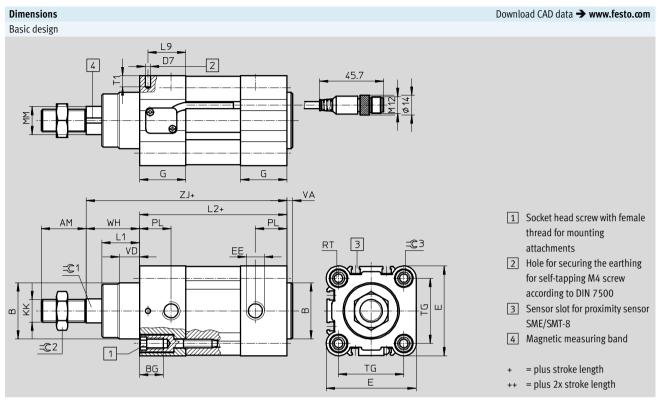
#### Off-set assembly, cable outlet upwards or downwards

A distance of X > 60 mm must be observed, if the offset is Y > 0 mm and the cable outlet is up or down.

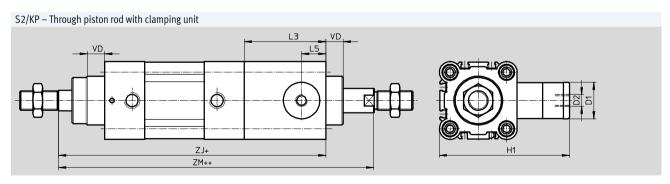




Technical data



# S2 – Through piston rod + = plus stroke length + = plus 2x stroke length

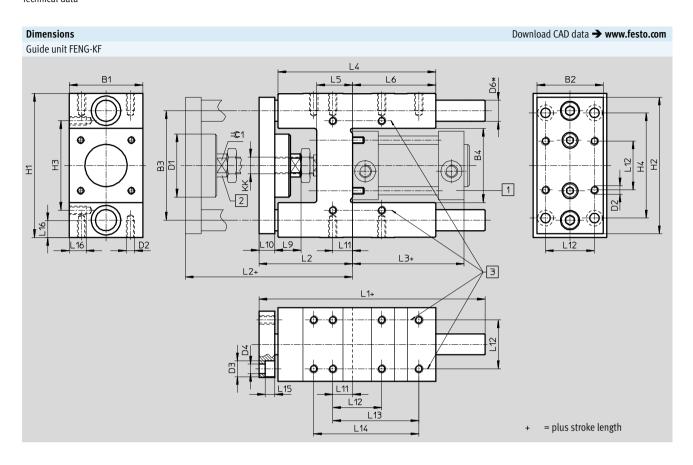






Ø [mm]	AM	A2 max.	B ∅ d11	BG	D1 Ø f9	D2	D7 Ø	E	EE	G	H1	
32	22	500	30	16	20	M5	3.7	45	G1/8	28	67	
40	24	500	35	16	24	G1/8	3.7	54	G1/4	33	88	
50	32	500	40	17	30	G1/8	3.7	64	G1/4	33	107	
63	32	500	45	17	38	G1/8	3.7	75	G3/8	40.5	123	
Ø	KK	L1	L2	L3	L5	L9	MM Ø	PL	RT	T1	TG	
[mm]							f8					
32	M10x1.25	18	94	45	14	22.5	12	15.6	M6	8	32.5	
40	M12x1.25	21.3	105	53	16	27	16	14	M6	8	38	
50	M16x1.5	26.8	106	67	20	27	20	14	M8	8	46.5	
63	M16x1.5	27	121	76	24	33	20	17	M8	8	56.5	
Ø	VA	VD	WH	Z	<u>ZJ</u>	Z	M	=©1	=©2	=	<del>2</del> 3	
[mm]					KP		KP					
32	4	10	26	120	165	148	193	10	16	(	5	
40	4	10.8	30	135	188	167	220	13	18	(	6	
50	4	14.3	37	143	210	183	250	17	24	3	3	
63	4	14.5	37	158	234	199	275	17	24	3	3	





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For Ø	B1	B2	В3	B4	D1	D2	D3	D4	D6	H1
					Ø		Ø	Ø	Ø	
[mm]	-0.3		±0.2	±0.3					h6	
32	50	45	74	50.5	44	M6	11	6.6	12	97-0.4
40	58	54	87	58.5	44	M6	11	6.6	16	115-0.4
50	70	63	104	70.5	60	M8	15	9	20	137 <sub>-0.5</sub>
63	85	80	119	85.5	60	M8	15	9	20	152 <sub>-0.5</sub>
For Ø	H2	Н3	H4	KK	L1	L2	L3	L4	L5	L6
[mm]		±0.2	±0.2							
32	90	61	78	M10x1.25	155	67+5	94	125	24	76
40	110	69	84	M12x1.25	170	75 <sub>+5</sub>	105	140	28	81
50	130	85	100	M16x1	188	89+10	106	150	34	79
63	145	100	105	M16x1	220	89+10	121	182	34	111
For Ø	L9	L10	L11	L12	L13	L14	L15	L16	=	<b>\$</b> 1
[mm]				±0.2	±0.2	±0.2				
32	20	12	4.3	32.5	70.3	78	6.5	12	15	
40	22	12	11	38	84	-	6.5	14	15	
50	25	15	18.8	46.5	81.8	100	9	16	1	9
63	25	15	15.3	56.5	105	-	9	16	1	9

# Standard cylinders DNCI, with measured-value transducer DADE Ordering data – Modular products



0	rdering table								
Pi	ston Ø		32	40	50	63	Condi-	Code	Enter
							tions		code
M	Module No.		535411	535412	535413	535414			
	Function		Standard cylinder with integrated displacement encoder, non-rotating piston rod					DNCI	DNCI
	Piston Ø	[mm]	32	40	50	63			
	Stroke	[mm]	10 1250	0 1250					
	Cushioning		Elastic cushioning ring	Elastic cushioning rings/plates at both ends				-P	-P
Ψ	Position sensing For proximity sensor						-A	-A	

Transfer order co	oae							
	DNCI	_	_	_	P	_	Α	] _

# Standard cylinders DNCI, with measured-value transducer DADE Ordering data – Modular product

The piston rod is only extended at the front (side closest to the measuring head) in



2 **K8** 

Ordering table							
Piston Ø	32	40	50	63	Condi- tions	Code	Enter code
O Piston rod type	O Piston rod type Through piston rod						
Piston rod extended at [mm]	1 500	1 500					
front							
Clamping unit	Clamping unit Attached						
Guide Guide unit with ball bearing guide on the sensor head side						-FENG	
Measured-value transducer Output 0 10 V						-MU	
Output 4 20 mA						-MI	
Measuring head No measuring head						-MS	

3 **KP** 

4 FENG

Can only be combined with piston rod type S2

Maximum stroke length 500 mm

Note 5 In the case of repairs, the standard cylinder can be ordered without a measuring head (→ code MS). The existing measuring head

combination with piston rod type S2.

new standard cylinder (→ operating instructions for DNCI).

can then be installed in the

	Transfer order code						
-[		-	-	-[	-	-	



Technical data

Measured-value transducer DADE-MVC-010 DADE-MVC-420 (Order code MU, MI) The measured-value transducer converts sensor signals from the standard cylinder DNCI into a voltage signal of 0 ... 10 V or a current signal of 4 ... 20 mA. These signals can be evaluated by a PLC with an appropriate signal input.



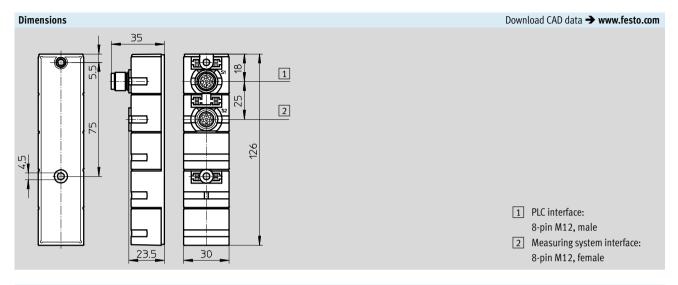
General technical data						
Type of mounting	With through-hole					
Mounting position	Any					
Protection against short circuit	Yes					
Protection against incorrect polarity	Yes					
Diagnostic function	Indication via LED					

General electrical data		
Analogue output	[V]	0 10 (according to EN 61131-2)
	[mA]	4 20 (according to EN 61131-2)
Nominal operating voltage	[V DC]	24 ±25%
Residual ripple	[%]	4 (at 50 Hz)
Current consumption at nominal	[mA]	20 30
operating voltage		
Switching logic at outputs		PNP
Switching logic at inputs		PNP
Debounce time at inputs	[ms]	3
Linearity error FS		0.2%

Operating and environmental conditions						
Ambient temperature [°C]	0 55					
Protection class	IP65					
Relative air humidity	95% non-condensing					
CE marking (see declaration of conformity)	To EU EMC Directive					
Corrosion resistance class CRC <sup>1)</sup>	1					
Product weight [g]	128					
Note on material for housing	Polybutylene terephthalate					

<sup>1)</sup> Corrosion resistance class CRC 1 to Festo standard FN 940070
Low corrosion stress. For dry indoor applications or transport and storage protection. Also applies to parts behind covers, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

**FESTO** 



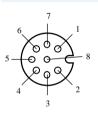
#### Pin allocation

PLC interface



	5
4	2
4\	
X	L.X e
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- / - '	
5-+	
\ '1	: 17

Measuring system	interface
measuring system	IIILEITALE



Pin	Function	Cable colour
1	24V	White
2	Analogue measurement signal	Brown
3	Reference output	Green
4	0 V measurement signal	Yellow
5	Reference input	Grey
6	Calibration input	Pink
7	Ready output	Blue
8	0 V power supply and inputs/	Red
	outputs	

Pin	Function
1	Ub
2	0 V
3	Signal sine +
4	Signal sine –
5	Signal cosine –
6	Signal cosine +
7	Screening / earth
8	-

Ordering data									
		Description	Part no.	Туре					
Measured-value transducer	Measured-value transducer								
	With voltage signal	0 10 V	542117	DADE-MVC-010					
	With current signal	4 20 mA	542118	DADE-MVC-420					
Accessories				Technical data → Internet: sim					
	Connecting cable	PLC connecting cable (length 2 m)	525616	SIM-M12-8GD-2-PU					
		PLC connecting cable (length 5 m)	525618	SIM-M12-8GD-5-PU					