## **Cushioning components**







Function	Туре	Version	Brief description	Area of application
Shock	Elastomer	absorber		
absorber	DYEF-Y1		Mechanical shock absorber with flexible rubber buffer	Mini slide DGSL
		Sall Market	Cushioning stroke cannot be adjusted	
		O. D. C.	No fixed stop	
			Continuous mounting thread with internal hex	
	DYEF-Y1F		Mechanical shock absorber with flexible rubber buffer	<ul> <li>Mini slide DGSL</li> </ul>
			Cushioning stroke can be adjusted	<ul> <li>Swivel module DSM-B</li> </ul>
		مالات	With fixed stop	
			Continuous mounting thread with internal hex	
	Adjustable	e	a Hudraulia shaak ahaayhay with angina yatuya	
	DYSR		Hydraulic shock absorber with spring return     Adjustable such india hardness	_
		0	Adjustable cushioning hardness	
	Self-adjus	sting		
	YSR-C		Hydraulic shock absorber with path-controlled flow control function	<ul> <li>Linear drive DGPL</li> </ul>
			Rapidly increasing cushioning force curve	<ul> <li>Linear drive DGC</li> </ul>
			Short cushioning stroke	Linear unit SLE
			Suitable for rotary drives	
			Maintenance-free	
			Continuous mounting thread	
	DYSC		Hydraulic shock absorber with path-controlled flow control function	Swivel module DSM-B
			Rapidly increasing cushioning force curve	Swivel/linear unit DSL-B
			Short cushioning stroke	
			Suitable for rotary drives	
			Maintenance-free	
			Metal end position at the housing	
	1/08/1/		Continuous mounting thread with internal hex	
	YSRW		Hydraulic shock absorber with path-controlled flow control function	Linear drive DGC
			Slowly increasing cushioning force curve	Handling module HSP,
			Long cushioning stroke     Control of the strong stroke	HSW
			Suitable for low-vibration operation	
			Short cycle times possible	
			Maintenance-free	
	DVCW		Continuous mounting thread with spanner flat	- Mini alida DCCI
	DYSW		Hydraulic shock absorber with path-controlled flow control function	Mini slide DGSL
		(Samuel )	Slowly increasing cushioning force curve     Long such increasing charles	Handling module HSW
			Long cushioning stroke     Suitable for low vibration exerction	
			Suitable for low-vibration operation     Short guild times possible.	
			Short cycle times possible     Maintenance for	
			Maintenance-free     Match and an iffice at the leave in a	
			Metal end position at the housing	
			Continuous mounting thread with internal hex	



Size	Stroke	Energy absorption per stroke	Position sensing	Free of copper, PTFE and silicone	→ Page/Internet
	[mm]	D1			
Elastomer absorber			L		
M4, M5, M6, M8, M10,	0.9, 1.0, 1.2, 1.3, 1.5	0.015 0.55			7
M12, M14, M16			_	_	
				_	
M4, M5, M6, M8, M10,	1.7, 2.8, 3.1, 3.4, 3.7,	0.005 1.2			10
M12, M14, M16, M22	4.2, 5, 4.8, 7		_	_	
				_	
Adjustable	0 40 00 05 (0 (0	1	<del> </del>		
8, 12, 16, 20, 25, 32	8, 12, 20, 25, 40, 60	4 384			14
l			_	_	
					1
Self-adjusting	/ 5 0 40 42 20 25	0 ( 200	T	T	140
4, 5, 7, 8, 10, 12, 16, 20, 25, 32	4, 5, 8, 10, 12, 20, 25, 40, 60	0.6 380			18
25, 52	40, 60			•	
			_	Size	
				4 20	
4, 5, 7, 8, 12, 16, 20, 25	4, 5, 8, 12, 18, 25	0.6 25			22
			_	•	
5 5 0 40 40 46 00	2 42 44 45 22 24 24	1.0 70			
5, 7, 8, 10, 12, 16, 20	8, 10, 14, 17, 20, 26, 34	1.3 70			26
			_	•	
4, 5, 7, 8, 10, 12	6, 8, 10, 14, 17, 20	0.8 12			30
., ,, ,, 0, 10, 12	0, 0, 10, 17, 17, 20	12			
			_	•	
			_	_	



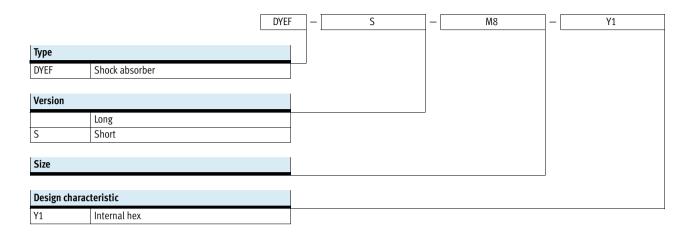
Function	Туре	Version	Brief description	Area of application
Stop	Self-adjust	ing		
element	YSRWJ		Cushioning with self-adjusting, progressive hydraulic shock absorber (YSRW)	-
			Slowly increasing cushioning force curve	
		<b>S</b>	Adjustable cushioning stroke	
			End-position sensing with proximity sensors SME/SMT-8	
			Precision end-position adjustment	
			• Stop elements YSRWJ can be used for a wide variety of applications in handling and	
			assembly technology	
Hydraulic	Adjustable			
cushioning	DYHR		Hydraulic cushioning cylinder for constant, slow braking speeds across the entire	_
cylinder		550	stroke	
		S S S S S S S S S S S S S S S S S S S	Braking speed can be precisely adjusted	
			A built-in compression spring returns the piston rod to the initial position	
			Suitable for slow feed speeds in the range up to 0.1 m/s	



Size	Stroke	Energy absorption per stroke	Position sensing	Free of copper, PTFE and silicone	→ Page/Internet
	[mm]	[J]			
Self-adjusting					
5, 7, 8	8, 10, 14	1 3			34
			_		
			•	_	
Adjustable					
16, 20, 25, 32	20, 25, 40, 50, 60	32 384			38
			-	-	

# **Shock absorbers DYEF- ... -Y1, without fixed stop** Type codes





# Shock absorbers DYEF- ... -Y1, without fixed stop Technical data



- **Ø** - Size M4 ... M16

Stroke length 0.9 ... 1.5 mm



General technical data												
Size			M4	M5	M6	M8	M10	M12	M14	M16		
Stroke [mm]		0.9	1.5	1.5	1.3	1	1.2	1.2	1.3			
Mode of operation			Elastomer ci	ushioning w	ithout metal f	ixed stop						
Cushioning	Not adjustal	Not adjustable										
Cushioning length [mm]		0.9	1.5	1.5	1.3	1	1.2	1.2	1.3			
Type of mounting		Via lock nut	Via lock nut									
Max. impact velocity		[m/s]	0.8	0.8								
Mounting position			Any	Any								
Product weight		[g]	2.1	3.6	6	14	23	45.5	82.5	106		
	S	[g]	1.1	2	3	8.6	12	15	31	40		
Ambient temperature [°C]			0 +60	0 +60								
Corrosion resistance class CRC <sup>1)</sup>			2	2								

<sup>1)</sup> Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Energy [J]								
Size	M4	M5	M6	M8	M10	M12	M14	M16
Max. energy absorption per stroke	0.015	0.05	0.08	0.12	0.25	0.35	0.45	0.55

Mass range [kg]								
Size	M4	M5	M6	M8	M10	M12	M14	M16
Mass range up to	0.15	0.35	0.7	1	2	3	5	7

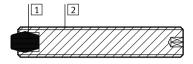
### Shock absorbers DYEF-...-Y1, without fixed stop



Technical data

#### Materials

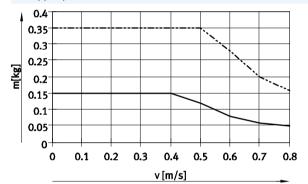
Sectional view

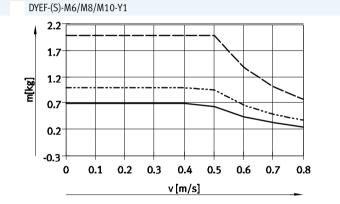


Shock	absorber	
1	Buffer	Nitrile rubber
2	Housing	High-alloy steel
-	Seals	Nitrile rubber
	Note on materials	Free of copper, PTFE and silicone
		RoHS-compliant RoHS-compliant

#### Impact velocity dependent on mass m

DYEF-(S)-M4/M5-Y1

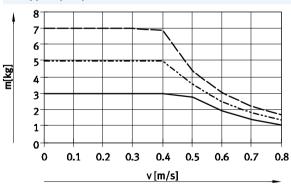




DYEF-(S-)M4-Y1
DYEF-(S-)M5-Y1

DYEF-(S-)M6-Y1
DYEF-(S-)M8-Y1
DYEF-(S-)M10-Y1

#### DYEF-(S)-M12/M14/M16-Y1



DYEF-(S-)M12-Y1
DYEF-(S-)M14-Y1
DYEF-(S-)M16-Y1

# Shock absorbers DYEF-...-Y1, without fixed stop Technical data







Size	B1	D1	DYEF-M	1 DYEF-S-M	L2	=©1	=©2	Max. tightening torque =€1
			DILI-W	DIEI-3-M	+0.3			[Nm]
M4	2.2	M4x0.5	22	12	0.9	7	1.3	0.5
M5	2.7	M5x0.5	26	14.5	1.8	8	1.5	0.8
M6	2.5	M6x0.5	30	15	1.8	8	2	1
M8	3	M8x1	38	23.5	2	10	2.5	2
M10	3.5	M10x1	41	21	1.8	13	3	3
M12	4	M12x1	54	20	2	15	4	5
M14	5	M14x1	72	28	2	17	4	8
M16	5	M16x1	75	31.5	2	19	5	20

Ordering	g data			
Size	Part No.	Туре		
DYEF-M	– Long version			
M4	1179810	DYEF-M4-Y1		
M5	1179818	DYEF-M5-Y1		
M6	1179831	DYEF-M6-Y1		
M8	1179834	DYEF-M8-Y1		
M10	1179837	DYEF-M10-Y1		
M12	1179840	DYEF-M12-Y1		
M14	1179863	DYEF-M14-Y1		
M16	1179879	DYEF-M16-Y1		
	·			
DYEF-S-N	N – Short version			
M4	1152500	DYEF-S-M4-Y1		
M5	1152507	DYEF-S-M5-Y1		
M6	1152524	DYEF-S-M6-Y1		
M8	1152536	DYEF-S-M8-Y1		
M10	1152959	DYEF-S-M10-Y1		
M12	1153004	DYEF-S-M12-Y1		
M14	1153017	DYEF-S-M14-Y1		
M16	1153023	DYEF-S-M16-Y1		

# **Shock absorbers DYEF- ... -Y1F, with fixed stop** Type codes



		DYEF	_	M8	_	Y1	F	
Туре								
DYEF	Shock absorber							
Size								
Design char	acteristic							
Y1	Internal hex							
Stop								
F	With fixed stop							

### Shock absorbers DYEF- ... -Y1F, with fixed stop



Technical data

- **Ø** - Size M4 ... M22

Stroke length



General technical data										
Size		M4	M5	M6	M8	M10	M12	M14	M16	M22
Stroke	[mm]	1.7	2.8	3.1	3.4	3.7	4.2	5	4.8	7
Mode of operation		Elastomer	cushioning w	ith metal fixe	d stop					
Cushioning		Adjustable	!							
Cushioning length	[mm]	1.7	2.8	3.1	3.4	3.7	4.2	5	4.8	7
Type of mounting		Via lock nu	ıt						·	
Max. impact velocity	[m/s]	0.8								
Mounting position		Any								
Product weight	[g]	1.6	2.9	5.1	11.9	19.7	39.6	77.3	104	200
Ambient temperature	[°C]	0 +60				•	•			•
Corrosion resistance class CRC <sup>1)</sup>		2								

<sup>1)</sup> Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Force [N]									
Size	M4	M5	M6	M8	M10	M12	M14	M16	M22
Min. insertion force <sup>1)</sup>	15	30	40	60	70	100	150	180	500

<sup>1)</sup> This is the minimum force that must be applied so that the shock absorber is pushed precisely into the retracted end position. This value is reduced correspondingly in the event of an extended external end position or a reduction in the cushioning stroke.

Energy [J]									
Size	M4	M5	M6	M8	M10	M12	M14	M16	M22
Max. energy absorption per stroke	0.005	0.02	0.03	0.04	0.06	0.12	0.2	0.25	1.2

Mass range [kg]									
Size	M4	M5	M6	M8	M10	M12	M14	M16	M22
Mass range up to	0.15	0.25	0.4	0.6	1.2	1.8	3	5	15

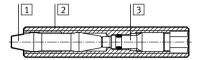
### Shock absorbers DYEF- ... -Y1F, with fixed stop



Technical data

#### Materials

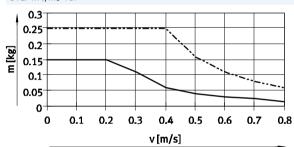
Sectional view



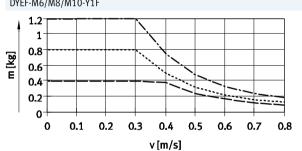
Shock	absorber	
1	Buffer	Nitrile rubber
2	Adjustable sleeve	High-alloy steel
3	Setting piece	High-alloy steel
-	Seals	Nitrile rubber
	Note on materials	Free of copper, PTFE and silicone
		RoHS-compliant

#### Impact velocity as a function of mass m

DYEF-M4/M5-Y1F



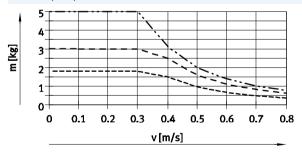




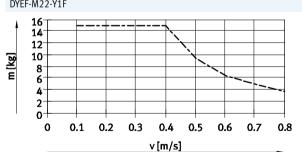
DYEF-M4 ----- DYEF-M5

-- DYEF-M6 ----- DYEF-M8 —--- DYEF-M10

#### DYEF-M12/M14/M16-Y1F



DYEF-M22-Y1F



---- DYEF-M12 - - - DYEF-M14

---- DYEF-M16

---- DYEF-M22

# **Shock absorbers DYEF- ... -Y1F, with fixed stop** Technical data





Size	B1	D1	L1	L2	=©1	=©2	=©3	Max. tightening torque <€1
				+0.3				[Nm]
M4	2.2	M4x0.5	22	1.7	7	1.3	2.5	0.5
M5	2.7	M5x0.5	26	2.8	8	1.5	3	0.8
M6	2.5	M6x0.5	30	3.1	8	2	4	1
M8	3	M8x1	38	3.4	10	2.5	5	2
M10	3.5	M10x1	41	3.7	13	3	6	3
M12	4	M12x1	54	4.2	15	4	8	5
M14	5	M14x1	72	5	17	4	8	8
M16	5	M16x1	75	4.8	19	5	10	20
M22	5	M22x1.5	78	7	27	5	10	35

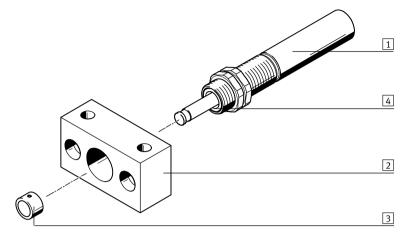
Ordering d	lata	
Size	Part No.	Туре
M4	548370	DYEF-M4-Y1F <sup>1)</sup>
M5	548371	DYEF-M5-Y1F
M6	548372	DYEF-M6-Y1F
M8	548373	DYEF-M8-Y1F
M10	548374	DYEF-M10-Y1F
M12	548375	DYEF-M12-Y1F
M14	548376	DYEF-M14-Y1F
M16	548377	DYEF-M16-Y1F
M22	1113706	DYEF-M22-Y1F

<sup>1)</sup> The scope of delivery for this size includes an Allen key.

**FESTO** 

Peripherals overview and type codes

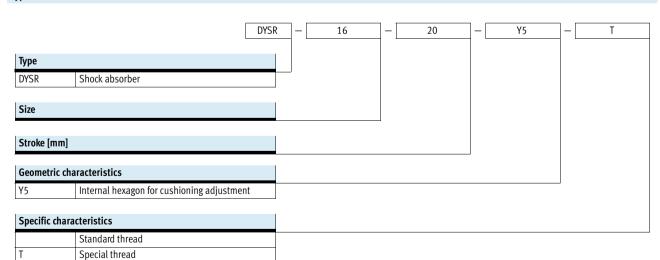
#### Peripherals overview



Access	ories		
	Туре	Brief description	→ Page/Internet
1	Shock absorber DYSR	Hydraulic shock absorber with adjustable cushioning characteristics	15
2	Mounting flange YSRF	Mounting option for shock absorber	42
3	Buffer YSRP	For protecting the piston rod	44
4	Wiper seal <sup>1)</sup> ; hardened piston rod <sup>2)</sup>	The wiper seal (prevents the ingress of dirt) and the hardened piston rod (protects against scratches) greatly increase the service life	_

- As of size 12
   As of size 16

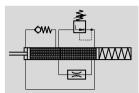
#### Type codes



**FESTO** 

Technical data

#### Function









General technical data									
Size		8	12	16	20	25	32		
Stroke	[mm]	8	12	20	25	40	60		
Mode of operation		Hydraulic shock	absorber with sprin	g return					
		Single acting, pu	shing						
Cushioning Adjustable, force-dependent, hard characteristic curve									
Cushioning length	[mm]	8	12	20	25	40	60		
Type of mounting		Via lock nut							
Impact velocity	[m/s]	0.1 3							
Mounting position		Any							
Product weight	[g]	60	105/120 <sup>1)</sup>	200/250 <sup>1)</sup>	355/425 <sup>1)</sup>	715	1,355		
Ambient temperature	[°C]	-10 +80	<u>*</u>						
Corrosion resistance class	CRC <sup>2)</sup>	1	1						

<sup>1)</sup> Applies to shock absorbers with special thread T

Corrosion resistance class 1 according to Festo standard 940 070

Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers

Reset time [s]						
Size	8	12	16	20	25	32
Reset time <sup>1)</sup>	≰[0.2		≤ 0.3		≤ 0.4	≤ 0.6

<sup>1)</sup> The specified technical data refers to ambient temperature. At  $-10\,^{\circ}$ C, the reset time can be up to 1 s for sizes 12, 16 and up to 3 s for sizes 8, 20, 25, 32

Force [N]									
Size	8	12	16	20	25	32			
Min. insertion force <sup>1)</sup>	18	38	66	110	155	175			
Max. stop force <sup>2)</sup> in the end positions	400	900	1,600	2,500	4,000	6,400			
Min. resetting force <sup>3)</sup>	1.8	4.5	5.4	9	12.5	18			

<sup>1)</sup> This is the minimum force that must be applied so that the shock absorber is pushed precisely into the retracted end position. This value is reduced correspondingly with an extended external end position 2) If the maximum stop force is exceeded, a fixed stop (e.g. YSRA) must be fitted 0.5 mm before the end of stroke

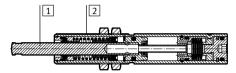
<sup>3)</sup> This is the maximum force that can act on the piston rod, allowing for full extension of the shock absorber (e.g. protruding bolt)

Energy [J]									
Size	8	12	16	20	25	32			
Max. energy absorption per stroke	4	10.8	32	62.5	160	384			
Max. energy absorption per hour	24,000	60,000	100,000	135,000	220,000	330,000			
Max. residual energy	0.01	0.05	0.16	0.32	0.8	2			

Technical data

#### Materials

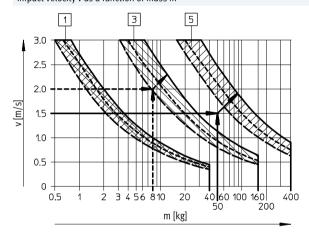
Sectional view

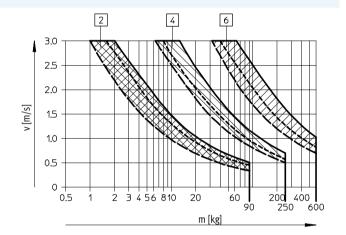


Size		8	12	16	20	25	32		
1	Piston rod	High-alloy steel		High-alloy steel, hardened					
2	Housing	High-alloy steel	ligh-alloy steel Galvanised steel						
-	Buffer	Polyacetal	_						
-	Seals	Nitrile rubber							
	Note on materials	RoHS-compliant							

#### Selection graph for shock absorbers with infinitely adjustable cushioning DYSR

Impact velocity v as a function of mass m





Three force curves are shown for each shock absorber. Interim values must be calculated by averaging.

The arrows relate to the examples starting on page 48.

1 DYSR-8-8

4 DYSR-20-25

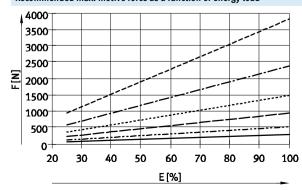
DYSR-12-12DYSR-16-20

5 DYSR-25-40

6 DYSR-32-60

Shock absorber	Force A =	Force A =	Force A =
DYSR-8-8	0 N	100 N	200 N
DYSR-12-12	0 N	200 N	500 N
DYSR-16-20	0 N	500 N	800 N
DYSR-20-25	0 N	800 N	1,200 N
DYSR-25-40	0 N	1,200 N	2,000 N
DYSR-32-60	0 N	2,000 N	3,000 N

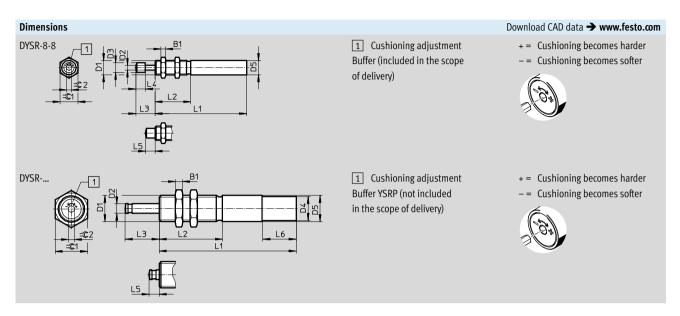
#### Recommended max. motive force as a function of energy load



DYSR-8-8-Y5
DYSR-12-12-Y5
DYSR-16-20-Y5
DYSR-20-25-Y5
DYSR-25-40-Y5
DYSR-32-60-Y5

Technical data





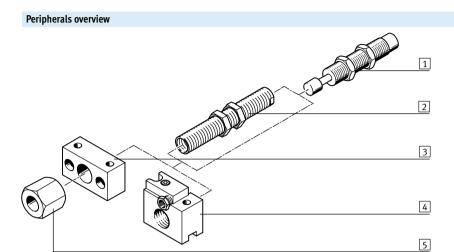
Туре	B1	D1	D2 Ø	D3 Ø	D4 Ø	D5 Ø	L1	L2
				±0.2	+0.15	+0.15/-0.1		±0.1
DYSR-8-8-Y5	4	M12x1	4	8	-	12	77±0.1	30
DYSR-12-12-Y5	5	M15x1	6	_		15	97±0.1	36
DYSR-12-12-Y5-T	)	M16x1	б	_	_	16	97±0.1	30
DYSR-16-20-Y5	6	M20x1.25	8	-	-	20	115±0.1	53
DYSR-16-20-Y5-T	0	M22x1.5	0		20	22	115±0.1	99
DYSR-20-25-Y5	8	M24x1.25	10	-	-	24	138±0.1	60
DYSR-20-25-Y5-T	٥	M26x1.5	10		24	26	130±0.1	60
DYSR-25-40-Y5	10	M30x1.5	12	-	28.8	30	178±0.1	80
DYSR-32-60-Y5	12	M37x1.5	15	-	34.8	37	230±0.15	108

Туре	L3	L4	L5	L6	=©1	=©2	Max. tightening torque =©1
		±0.2		±0.2			[Nm]
DYSR-8-8-Y5	16.2+0.6/-0.45	8	8+0.5/-0.35	-	15	4	5
DYSR-12-12-Y5	10 / 025/ 02		6 4 0 151 0 1	-	19	5	20
DYSR-12-12-Y5-T	18.4+0.35/-0.2	_	6.4+0.45/-0.4		19	5	20
DYSR-16-20-Y5	20 5 0 1/ 00		0.5 0.5/0.4	-	24	5	2.5
DYSR-16-20-Y5-T	28.5+0.4/-0.3	_	8.5+0.45/-0.4	28	27	5	35
DYSR-20-25-Y5	25 6 0 11 0 2		10 6 0 (5) 0 (	-	30	5	60
DYSR-20-25-Y5-T	35.6+0.4/-0.3	_	10.6+0.45/-0.4	28	32	5	60
DYSR-25-40-Y5	52.8+0.4/-0.3	-	12.8+0.45/-0.4	28	36	6	80
DYSR-32-60-Y5	76+0.5/-0.4	-	16+0.5/-0.4	28	46	6	100

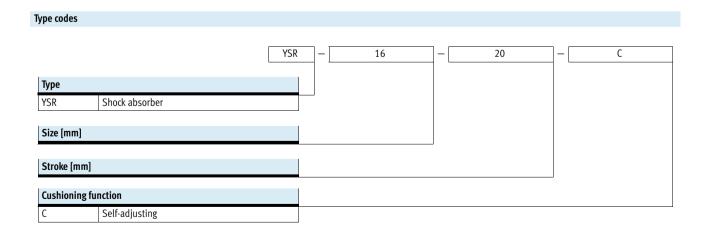
Ordering data	1	
Size	Part No.	Туре
8	1138641	DYSR-8-8-Y5
12	1138642	DYSR-12-12-Y5
	1138643	DYSR-12-12-Y5-T
16	1138644	DYSR-16-20-Y5
	1138645	DYSR-16-20-Y5-T
20	1138646	DYSR-20-25-Y5
	1138647	DYSR-20-25-Y5-T
25	1138648	DYSR-25-40-Y5
32	1138649	DYSR-32-60-Y5



Peripherals overview and type codes



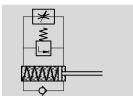
Access	ories		
	Туре	Brief description	→ Page/Internet
1	Shock absorber	Hydraulic shock absorber with rapidly increasing cushioning force curve	19
	YSR-C		
2	Reducing sleeve	To improve the cushioning performance in the case of underload, the built-in shock	45
	DAYH	absorber can be replaced by the next smallest shock absorber with the help of the	
		reducing sleeve	
3	Mounting flange	Mounting option for shock absorber	42
	YSRF		
4	Mounting flange	Mounting option for shock absorber with attached stop sleeve and position sensing	43
	YSRF-S		
5	Stop limiters	Stroke limiter for shock absorber	44
	YSRA		
-	Inductive proximity sensor	For mounting flange YSRF-S	45
	SIEN		



**FESTO** 

Technical data







- Stroke length 4 ... 60 mm



General technical data											
Size		4	5	7	8	10	12	16	20	25	32
Stroke	[mm]	4	5	5	8	10	12	20	25	40	60
Mode of operation		Hydraulic	shock absorb	ers with ret	urn spring						
		Single acti	ng, pushing								
Cushioning		Self-adjus	table								
Cushioning length	[mm]	4	5	5	8	10	12	20	25	40	60
Type of mounting		With lockn	ut			•					
Impact velocity	[m/s]	0.05 2		0.05 3							
Mounting position		Any									
Product weight	[g]	5	8	16	32	51	74	185	318	600	1220
Ambient temperature	[°C]	-10 +80	)	*	•		•	•	•	•	•
Corrosion resistance class	CRC <sup>1)</sup>	2									

<sup>1)</sup> Corrosion resistance class 2 to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Reset time [s]										
Size	4	5	7	8	10	12	16	20	25	32
Reset time <sup>1)</sup>	≤ 0.2						≤ 0.3		≤ 0.4	≤ 0.5

<sup>1)</sup> The specified technical data refers to ambient temperature. At higher temperatures in the 80 °C range, the max. mass and the cushioning work must be reduced by 50% approx. At -10 °C, the reset time may be up to 1 second

Forces [N]										
Size	4	5	7	8	10	12	16	20	25	32
Min. insertion force <sup>1)</sup>	6.5	7.5	10	18	25	35	60	100	140	160
Max. stop force <sup>2)</sup> in end positions	100	200	300	500	700	1,000	2,000	3,000	4,000	6,000
Min. resetting force <sup>3)</sup>	0.7	0.9	1.2	2.5	3.5	5	6	10	14	20

- 1) This is the minimum force that must be applied so that the shock absorber is pushed exactly into the retracted end position. This value is reduced correspondingly in the event of an extended external end-position
- 2) If the max. stop force is exceeded, a fixed stop (e.g. YSRA) 0.5 mm must be fitted before the end of stroke
- 3) This is the maximum force which may act upon the piston rod, allowing for full extension of the shock absorber (e.g. protruding stem)

Energies [J]										
Size	4	5	7	8	10	12	16	20	25	32
Max. energy absorption per stroke	0.6	1	2	3	6	10	30	60	160	380
Max. energy absorption per hour	5,600	8,000	12,000	18,000	26,000	36,000	64,000	92,000	150,000	220,000
Max. residual energy	0.006	0.01		0.02	0.03	0.05	0.16	0.32	0.8	2

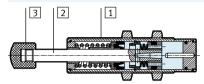
Mass range [kg]										
Size	4	5	7	8	10	12	16	20	25	32
Permissible mass range up to	1.2	1.5	5	15	25	45	90	120	200	400



Technical data

#### Materials

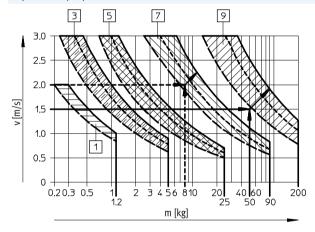
Sectional view

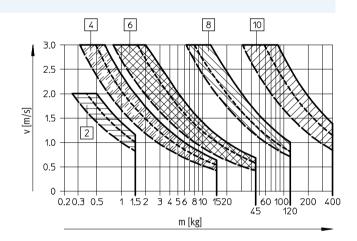


Piston	Ø	4	5	7	8	10	12	16	20	25	32	
1	Housing	High-alloy	steel			Galvanise						
2	Piston rod	High-alloy	steel			•						
3	Buffer	Polyamide								Steel with		
										polyuretha	ine	
-	Seals	Nitrile rubl	er, polyure	thane								
-	Note on materials	Free of copper, PTFE and silicone							-			
		Conforms t	Conforms to RoHS									

#### Selection graph for self-adjusting shock absorbers YSR-C

Impact velocity dependent on mass m





Three force curves are shown for each shock absorber. Interim values must be calculated by averaging. The

arrows relate to the examples starting on page → 49.

- 1 YSR-4-4-C YSR-5-5-C
- 5 YSR-12-12-C 6 YSR-16-20-C
- 2 YSR-7-5-C
- 7 YSR-20-25-C
- 3 YSR-8-8-C
- 8 YSR-25-40-C

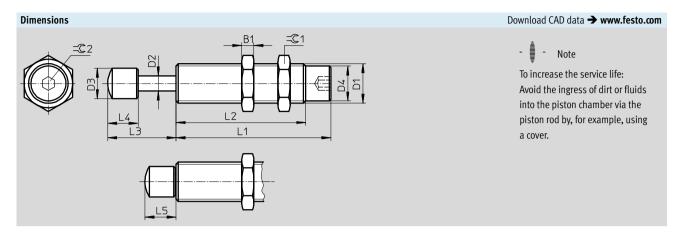
=		
4	YSR-10-1	0-0

10 YSR-32-60-C

Shock absorber	Force A =	Force A =	Force A =
YSR-4-4-C	0 N	-	50 N
YSR-5-5-C	0 N	50 N	100 N
YSR-7-5-C	0 N	100 N	200 N
YSR-8-8-C	0 N	100 N	200 N
YSR-10-10-C	0 N	150 N	300 N
YSR-12-12-C	0 N	200 N	500 N
YSR-16-20-C	0 N	500 N	800 N
YSR-20-25-C	0 N	800 N	1,200 N
YSR-25-40-C	0 N	1,200 N	2,500 N
YSR-32-60-C	0 N	2,000 N	4,000 N

**FESTO** 

Technical data



Size	B1	D1	D2	D3	D4	L1
[mm]			Ø	Ø	Ø	±0.1
4	2.5	M6x0.5	2	3.5 ±0.05	5.3 ±0.05	28.5
5	3	M8x1	2.5	4.7 ±0.05	6.7 ±0.05	29
7	3.5	M10x1	3	6 ±0.1	8.6 ±0.05	34
8	4	M12x1	4	8 ±0.2	10.4 ±0.1	46
10	5	M14x1	5	10 ±0.2	12.4 ±0.1	55
12	5	M16x1	6	12 ±0.2	14.5 ±0.1	64
16	6	M22x1.5	8	16 ±0.2	19.6 ±0.1	86
20	8	M26x1.5	10	20 ±0.2	23.8 ±0.1	104
25	10	M30x1.5	12	25 ±0.2	27.8 ±0.1	152
32	12	M37x1.5	15	32 ±0.2	34.8 ±0.1	205

Size	L2	L3	L4	L5	=©1	=©2	Max. tightening torque =© 1 [Nm]
[mm]	±0.3						
4	18.5	8.3 +0.6/-0.3	4 ±0.1	4.3 +0.35/-0.25	8	2	1
5	19	10.8 +0.6/-0.3	5.5 ±0.1	5.8 +0.55/-0.25	10		2
7	23	12.3 +0.7/-0.35	7 ±0.2	7.3 +0.55/-0.25	13		3
8	33	16.3 +0.7/-0.35	8 ±0.2	8.3 +0.55/-0.25	15		5
10	42	20.5 +0.7/-0.35	10 ±0.2	10.5 +0.55/-0.25	17		8
12	51	24.5 +0.7/-0.35	12 ±0.2	12.5 +0.55/-0.25	19	-	20
16	69	36.5 +0.7/-0.35	16 ±0.2	16.5 +0.55/-0.25	27		35
20	87	45.5 +0.7/-0.35	20 ±0.2	20.5 +0.55/-0.25	32		60
25	125	61.5 +1.25/-0.75	20.5 ±0.4	21.5 +0.95/-0.55	36		80
32	179	87 +1.25/-0.75	26 ±0.4	27 +0.95/-0.55	46		100

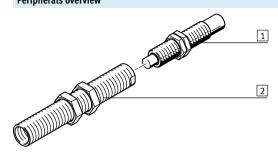
Ordering o	data	
Size	Part No.	Туре
[mm]		
4	540060	YSR-4-4-C <sup>1)</sup>
5	158981	YSR-5-5-C <sup>1)</sup>
7	160272	YSR-7-5-C <sup>1)</sup>
8	34571	YSR-8-8-C <sup>1)</sup>
10	191199	YSR-10-10-C <sup>1)</sup>
12	34572	YSR-12-12-C <sup>1)</sup>
16	34573	YSR-16-20-C <sup>1)</sup>
20	34574	YSR-20-25-C <sup>1)</sup>
25	160273	YSR-25-40-C
32	160274	YSR-32-60-C

<sup>1)</sup> Free of copper, PTFE and silicone



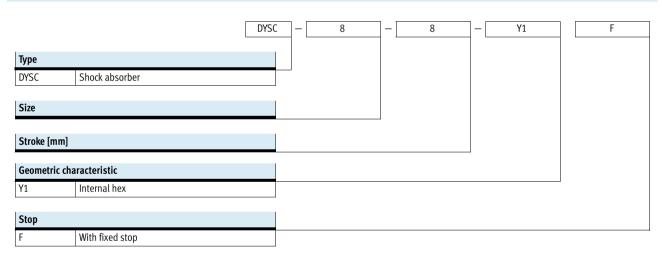
Peripherals overview and type codes

#### Peripherals overview



Access	ccessories									
	Туре	Brief description	→ Page/Internet							
1	Shock absorber DYSC	Hydraulic shock absorber with rapidly increasing cushioning force curve	23							
2	Reducing sleeve DAYH	To improve the cushioning performance in the case of underload, the built-in shock absorber can be replaced by the next smallest shock absorber with the help of the reducing sleeve	45							

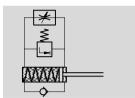
#### Type codes



**FESTO** 

Technical data







Stroke length 4 ... 25 mm



General technical data	General technical data								
Size		4	5	7	8	12	16	20	25
Stroke	[mm]	4	5	5	8	12	18	18	25
Mode of operation Hydraulic shock absorber with spring return									
		Single acting	Single acting, pushing						
Cushioning	ning Self-adjusting, hard characteristic curve								
Cushioning length	[mm]	4	5	5	8	12	18	16	25
Type of mounting		With lock nu	it			·	·		
Impact velocity	[m/s]	0.05 2		0.05 3					
Mounting position		Any							
Product weight	[g]	5	9	17	36	81	210	370	575
Ambient temperature	[°C]	-10 +80	-10 +80						
Corrosion resistance class CRC <sup>1)</sup> 2									

<sup>1)</sup> Corrosion resistance class 2 to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Reset time [s]								
Size	4	5	7	8	12	16	20	25
Reset time <sup>1)</sup>	≤ 0.2					≤ 0.3		

<sup>1)</sup> The specified technical data refers to ambient temperature. At higher temperatures in the 80 °C range, the max. mass and the cushioning work must be reduced by 50% approx. At -10 °C, the reset time may be up to 1 second

Forces [N]								
Size	4	5	7	8	12	16	20	25
Min. insertion force <sup>1)</sup>	6.5	7.5	10	18	35	60	100	140
Max. stop force <sup>2)</sup> in end positions	100	200	300	500	1,000	2,000	3,000	4,000
Min. resetting force <sup>3)</sup>	0.7	0.9	1.2	2.5	5	6	10	14

- 1) This is the minimum force that must be applied so that the shock absorber is pushed exactly into the retracted end position. This value is reduced correspondingly in the event of an extended external end position
- 2) If the max. stop force is exceeded, a fixed stop (e.g. YSRA) 0.5 mm must be fitted before the end of stroke
- 3) This is the maximum force which may act upon the piston rod, allowing for full extension of the shock absorber (e.g. protruding stem)

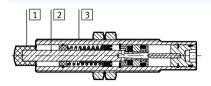
Energies [J]									
Size	4	5	7	8	12	16	20	25	
Max. energy absorption per stroke	0.6	1	2	3	10	25	38	100	
Max. energy absorption per hour	5,600	8,000	12,000	18,000	36,000	50,000	80,000	140,000	
Max. residual energy	0.006	0.01		0.02	0.05	0.16	0.32	0.8	

Mass range [kg]								
Size	4	5	7	8	12	16	20	25
Mass range up to	1.2	1.5	5	15	45	70	100	160

Technical data



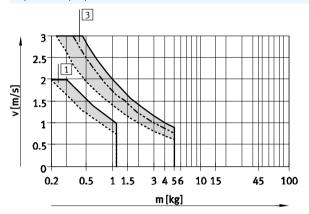
#### **Materials** Sectional view

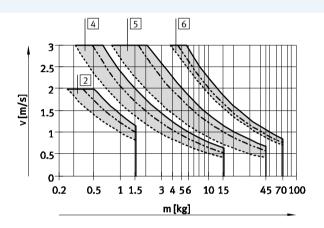


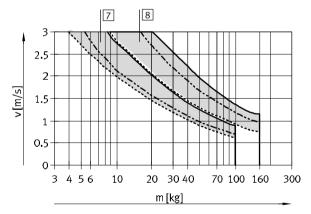
Size		4	5	7	8	12	16	20	25
1	Buffer	POM							
2	Piston rod	High-alloy steel							
3	Housing	High-alloy steel Galvanised steel							
-	Seals	NBR							
	Note on materials	Free of copper and PTFE							
		Conforms to RoHS							

#### Selection graph for self-adjusting shock absorbers DYSC

Impact velocity dependent on mass m







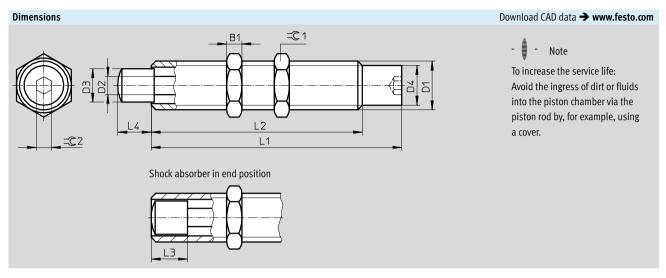
Three force curves are shown for each shock absorber. Interim values must be calculated by averaging.

- 1 DYSC-4-4-Y1F
- 2 DYSC-5-5-Y1F
- 3 DYSC-7-5-Y1F
- 4 DYSC-8-8-Y1F
- 5 DYSC-12-12-Y1F
- 6 DYSC-16-18-Y1F
- 7 DYSC-20-18-Y1F
- 8 DYSC-25-25-Y1F

Shock absorber	Force A =	Force A =	Force A =
DYSC-4-4-Y1F	0 N	-	50 N
DYSC-5-5-Y1F	0 N	50 N	100 N
DYSC-7-5-Y1F	0 N	100 N	200 N
DYSC-8-8-Y1F	0 N	100 N	200 N
DYSC-12-12-Y1F	0 N	200 N	500 N
DYSC-16-18-Y1F	0 N	500 N	800 N
DYSC-20-18-Y1F	0 N	800 N	1,200 N
DYSC-25-25-Y1F	0 N	1,200 N	2,500 N







Size	B1	D1	D2 Ø	D3 Ø	D4 Ø	L1	L2
[mm]						±0.1	+0.3/-0.2
4	2.5	M6x0.5	2	3.5 ±0.05	5.4 ±0.05	35.5	25.5
5	3	M8x1	2.5	4.7 ±0.05	6.7 ±0.05	38.6	28.6
7	3.5	M10x1	3	6 ±0.1	8.6 ±0.05	45.15	34.15
8	4	M12x1	4	7 ±0.1	10.4 ±0.1	59.05	46.05
12	5	M16x1	6	11 ±0.1	14.5 ±0.1	82.5	69.5
16	6	M22x1.5	8	15 ±0.1	19,6 ±0.1	110	93
20	8	M26x1.5	10	18.8 ±0.1	23.8 ±0.1	122	105
25	10	M30x1.5	12	22.8 ±0.1	27.8 ±0.1	165	137

Size	L3 <sup>1)</sup>	L4	=©1	<b>=</b> ©2	Max. tightening torque =€1
[mm]					[Nm]
4	4	4 +0.30/-0.24	8	2	1
5	5.5	5 +0.32/-0.28	10	2.5	2
7	7	5 +0.37/-0.28	13	3	3
8	8	8 +0.42/-0.33	15	4	5
12	12	12 +0.50/-0.35	19	5	20
16	17	18 +0.50/-0.35	27	5	35
20	20	18 +0.50/-0.35	32	6	60
25	22	25 +0.50/-0.35	36	8	80

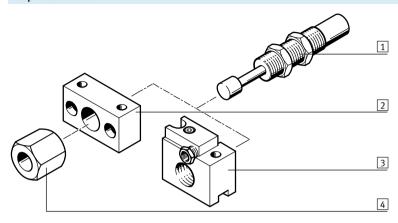
<sup>1)</sup> Buffer length

Ordering d	lata		
Size [mm]	Part No.	Туре	
4	570506	DYSC-4-4-Y1F	
5	548011	DYSC-5-5-Y1F	
7	548012	DYSC-7-5-Y1F	
8	548013	DYSC-8-8-Y1F	
12	548014	DYSC-12-12-Y1F	
16	553593	DYSC-16-18-Y1F	
20	2479149	DYSC-20-18-Y1F	
25	2480234	DYSC-25-25-Y1F	



Peripherals overview and type codes

#### Peripherals overview



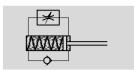
Access	sories		
	Туре	Brief description	→ Page/Internet
1	Shock absorber YSRW	Hydraulic shock absorber with progressive cushioning characteristic	27
2	Mounting flange YSRF	Mounting option for shock absorber	42
3	Mounting flange YSRF-S	Mounting option for shock absorber with attached stop sleeve and position sensing	43
4	Stop limiters YSRA	Stroke limiter for shock absorber	44
-	Inductive proximity sensor SIEN	For mounting flange YSRF-S	45

#### 

**FESTO** 

Technical data











General technical data									
Size		5	7	8	10	12	16	20	
Stroke	[mm]	8	10	14	17	20	26	34	
Mode of operation Hydraulic shock absorbers with return spring									
		Single acting	ingle acting, pushing						
Cushioning		Self-adjusta	Self-adjustable						
Cushioning length	[mm]	8	10	14	17	20	26	34	
Type of mounting		With locknut				<u> </u>	·		
Impact velocity	[m/s]	0.1 2	0.1 3						
Mounting position		Any							
Product weight	[g]	8	18	34	54	78	190	330	
Ambient temperature	[°C]	-10 +80	-10 +80						
Corrosion resistance class	2	2							

<sup>1)</sup> Corrosion resistance class 2 to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Reset time [s]							
Size	5	7	8	10	12	16	20
Reset time <sup>1)</sup>	≤ 0.2				≤ 0.3		

<sup>1)</sup> The specified technical data refers to ambient temperature. At higher temperatures in the 80 °C range, the max. mass and the cushioning work must be reduced by 50% approx. At -10 °C, the reset time may be up to 1 second

Forces [N]							
Size	5	7	8	10	12	16	20
Min. insertion force <sup>1)</sup>	7.5	10	18	25	35	60	100
Max. stop force <sup>2)</sup> in end positions	200	300	500	700	1,000	2,000	3,000
Min. resetting force <sup>3)</sup>	0.9	1.2	2.5	3.5	5	6	10

- 1) This is the minimum force that must be applied so that the shock absorber is pushed exactly into the retracted end position. This value is reduced correspondingly in the event of an extended external end-position
- 2) If the max. stop force is exceeded, a fixed stop (e.g. YSRA) 0.5 mm must be fitted before the end of stroke
- 3) This is the maximum force which may act upon the piston rod, allowing for full extension of the shock absorber (e.g. protruding stem)

Energies [J]							
Size	5	7	8	10	12	16	20
Max. energy absorption per stroke	1.3	2.5	4	8	12	35	70
Max. energy absorption per hour	10,000	15,000	21,000	30,000	41,000	68,000	100,000
Max. residual energy	0.01		0.02	0.03	0.05	0.16	0.32

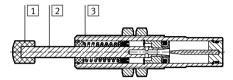
Mass range [kg]								
Size	5	7	8	10	12	16	20	
Permissible mass range up to	2	5	10	20	30	50	80	



Technical data

#### Materials

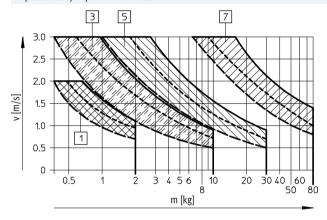
#### Sectional view

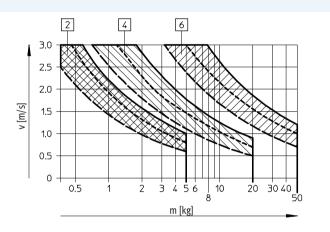


Size		5	7	8	10	12	16	20		
1	Buffer	Polyamide								
2	Piston rod	High-alloy steel								
3	Housing	High-alloy steel	High-alloy steel			Galvanised steel				
-	Seals	Nitrile rubber								
	Note on materials	Free of copper, PTFE and silicone								
		Conforms to RoHS								

#### Selection graph for self-adjusting shock absorbers with progressive characteristics YSRW

Impact velocity dependent on mass m





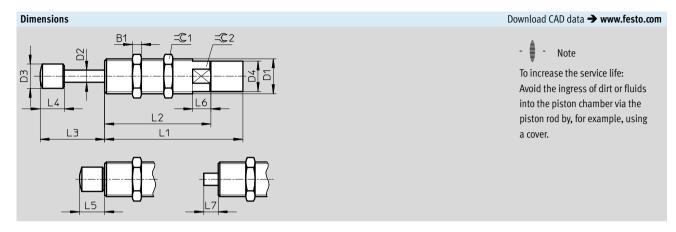
Three force curves are shown for each shock absorber. Interim values must be calculated by averaging.

- 1 YSRW-5-8
- 2 YSRW-7-10
- 3 YSRW-8-14
- 4 YSRW-10-17
- 5 YSRW-12-20
- 6 YSRW-16-26
- 7 YSRW-20-34

Shock absorber	Force A =	Force A =	Force A =
YSRW-5-8	0 N	50 N	100 N
YSRW-7-10	0 N	75 N	150 N
YSRW-8-14	0 N	100 N	200 N
YSRW-10-17	0 N	150 N	300 N
YSRW-12-20	0 N	200 N	400 N
YSRW-16-26	0 N	500 N	800 N
YSRW-20-34	0 N	800 N	1,200 N



Technical data



Size	B1	D1	D2 Ø	D3 ∅	D4 Ø	L1	L2	L3
[mm]						±0.1	±0.3	
5	3	M8x1	2.5	4.7 ±0.05	6.7 ±0.05	33.5	22.5	13.8 +0.6/-0.25
7	3.5	M10x1	3	6 ±0.1	8.6 ±0.05	41	30	17.3 +0.7/-0.25
8	4	M12x1	4	8 ±0.2	10.4 ±0.1	53	40	22.3 +0.7/-0.25
10	5	M14x1	5	10 ±0.2	12.4 ±0.1	62	49	27.5 +0.7/-0.25
12	5	M16x1	6	12 ±0.2	14.5 ±0.1	72.5	59.5	32.5 +0.7/-0.25
16	6	M22x1.5	8	16 ±0.2	20 ±0.1	91	70	42.5 +0.7/-0.35
20	8	M26x1.5	10	18.8 ±0.2	24 ±0.1	112	91	54.5 +0.7/-0.35

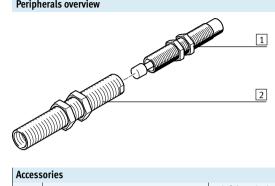
Size	L4	L5	L6	L7	<b>=</b> ©1	=©2	Max. tightening torque ∹©1
[mm]			+0.5				[Nm]
5	5.5 ±0.1	5.8 +0.35/-0.25	5	3.5 ±0.25	10	7	2
7	7 ±0.2	7.3 +0.35/-0.25	6	4.3 ±0.25	13	9	3
8	8 ±0.2	8.3 +0.4/-0.25	8	5.3 +0.3/-0.25	15	11	5
10	10 ±0.2	10.5 +0.4/-0.25	10	6.5 +0.3/-0.25	17	13	8
12	12 ±0.2	12.5 +0.4/-0.25	12	7.5 +0.3/-0.25	19	15	20
16	16 ±0.2	16.5 +0.4/-0.25	12	9.5 +0.3/-0.25	27	20	35
20	20 ±0.2	20.5 +0.4/-0.25	12	11.5 +0.3/-0.25	32	24	60

Ordering	data	
Size	Part No.	Туре
[mm]		
5	191192	YSRW-5-8
7	191193	YSRW-7-10
8	191194	YSRW-8-14
10	191195	YSRW-10-17
12	191196	YSRW-12-20
16	191197	YSRW-16-26
20	191198	YSRW-20-34



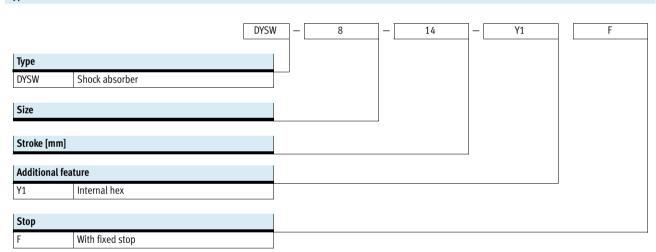
Peripherals overview and type codes

#### Peripherals overview



Access	ories		
	Туре	Brief description	→ Page/Internet
1	Shock absorber DYSW	Hydraulic shock absorber with rapidly increasing cushioning force curve	31
2	Reducing sleeve DAYH	To improve the cushioning performance in the case of underload, the built-in shock absorber can be replaced by the next smallest shock absorber with the help of the reducing sleeve	45

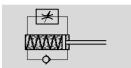
#### Type codes



**FESTO** 

Technical data











General technical data							
Size		4	5	7	8	10	12
Stroke	[mm]	6	8	10	14	17	20
Mode of operation		Hydraulic shock	absorber with sp	oring return	·		
		Single acting, pu	shing				
Cushioning		Self-adjusting, so	oft characteristic	curve			
Cushioning length	[mm]	6	8	10	14	17	20
Type of mounting		With lock nut				-	
Impact velocity	[m/s]	0.1 2		0.1 3			
Assembly position		Any		·			
Product weight	[g]	6	11	21	42	67	91
Ambient temperature	[°C]	-10 +80	•	•		•	·

Reset time [s]						
Size	4	5	7	8	10	12
Reset time <sup>1)</sup>	≤ 0.2					≤ 0.3

<sup>1)</sup> The specified technical data refers to ambient temperature. At higher temperatures in the 80 °C range, the max. mass and the cushioning work must be reduced by 50% approx. At -10 °C, the reset time may be up to 1 second

Forces [N]								
Size	4	5	7	8	10	12		
Min. insertion force <sup>1)</sup>	6.5	7.5	10	18	25	35		
Max. stop force <sup>2)</sup> in end positions	100	200	300	500	700	1,000		
(housing)								
Min. resetting force <sup>3)</sup>	0.7	0.9	1.2	2.5	3.5	5		

- 1) This is the minimum force that must be applied so that the shock absorber is pushed exactly into the retracted end position. This value is reduced correspondingly in the event of an extended external end position
- 2) If the max. stop force is exceeded, a fixed stop (e.g. YSRA) 0.5 mm must be fitted before the end of stroke
- 3) This is the maximum force which may act upon the piston rod, allowing for full extension of the shock absorber (e.g. protruding stem)

Energies [J]								
Size	4	5	7	8	10	12		
Max. energy absorption per stroke	0.8	1.3	2.5	4	8	12		
Max. energy absorption per hour	7,000	10,000	15,000	21,000	30,000	41,000		
Max. residual energy	0.006	0.01	0.01	0.02	0.03	0.05		

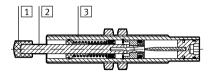
Mass range [kg]							
Size	4	5	7	8	10	12	
Mass range up to	1.2	2	5	10	20	30	



Technical data

#### Materials

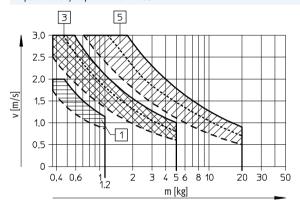
Sectional view

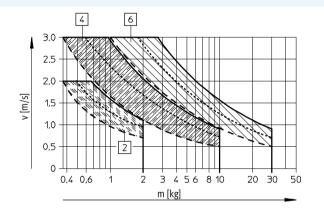


Size		4	5	7	8	10	12
1	Buffer	Polyacetate					
2	Piston rod	High-alloy steel					
3	Housing	High-alloy steel Galvanised steel					
-	Seals	Nitrile rubber					
	Note on materials	Free of copper, PTFE and silicone					
		Conforms to RoHS					

#### Selection graph for self-adjusting shock absorbers with progressive characteristics DYSW

Impact velocity dependent on mass m





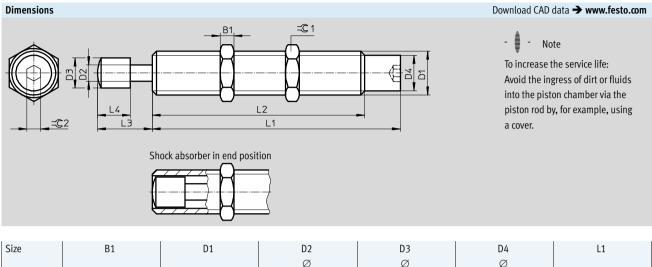
Three force curves are shown for each shock absorber. Interim values must be calculated by averaging.

- 1 DYSW-4-6-Y1F
- 2 DYSW-5-8-Y1F
- 3 DYSW-7-10-Y1F
- 4 DYSW-8-14-Y1F
- 5 DYSW-10-17-Y1F
- 6 DYSW-12-20-Y1F

Shock absorber	Force A =	Force A =	Force A =
DYSW-4-6-Y1F	0 N	-	50 N
DYSW-5-8-Y1F	0 N	50 N	100 N
DYSW-7-10-Y1F	0 N	75 N	150 N
DYSW-8-14-Y1F	0 N	100 N	200 N
DYSW-10-17-Y1F	0 N	150 N	300 N
DYSW-12-20-Y1F	0 N	200 N	400 N



Technical data



Size	B1	D1	D2 Ø	D3 Ø	D4 Ø	L1
[mm]						+0.1
4	2.5	M6x0.5	2	3.5±0.05	5.35±0.05	35.5
5	3	M8x1	2.5	4.7±0.05	6.7±0.05	43.1
7	3.5	M10x1	3	6±0.1	8.6±0.05	52.05
8	4	M12x1	4	7±0.1	10.4±0.1	66.05
10	5	M14x1	5	9±0.1	12.4±0.1	77.55
12	5	M16x1	6	11±0.1	14.4±0.1	90.75

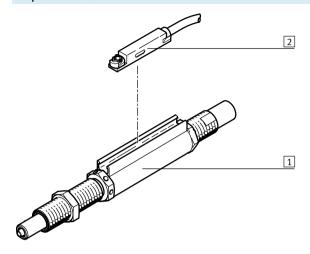
Size [mm]	L2 +0.3 -0.2	L3	L4	<b>=</b> ©1	=©2	Max. tightening torque =©1 [Nm]
4	25.5	6+0.30/-0.24	4±0.05	8	2	1
5	33.1	8+0.32/-0.28	5.5±0.1	10	2.5	2
7	41.05	10+0.37/-0.28	7±0.2	13	3	3
8	53.05	14+0.37/-0.28	8±0.2	15	4	5
10	64.55	17+0.37/-0.28	10±0.2	17	4	8
12	77.75	20+0.45/-0.30	12±0.2	19	5	20

Ordering data				
Size	Part No.	Туре		
[mm]				
4	548070	DYSW-4-6-Y1F		
5	548071	DYSW-5-8-Y1F		
7	548072	DYSW-7-10-Y1F		
8	548073	DYSW-8-14-Y1F		
10	548074	DYSW-10-17-Y1F		
12	548075	DYSW-12-20-Y1F		

## **Stop elements YSRWJ**Peripherals overview and type codes

**FESTO** 

#### Peripherals overview



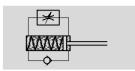
Access	Accessories				
	Туре	Brief description	→ Page/Internet		
1	Stop element	Hydraulic shock absorber with progressive cushioning characteristic.	35		
	YSRWJ	The cushioning length is adjustable			
2	Proximity switches	Sensing option for end positions	45		
	SME-/SMT-8				

#### Type codes YSRWJ 10 Α Туре YSRWJ Shock absorber Size Stroke [mm] Position sensing Position sensing

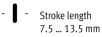
## **Stop elements YSRWJ** Technical data

**FESTO** 

#### Function









General technical data				
Size		5	7	8
Stroke	[mm]	8	10	14
Mode of operation		A piston rod in front of the s	shock absorber transmits the force	to the shock absorber. This serves as the end stop and
		actuates the proximity sens	sor via a magnet mounted on it	
		Single acting, pushing		
Cushioning		Self-adjustable		
Cushioning length	[mm]	8	10	14
Type of mounting		With locknut		
Position sensing		Via proximity sensor		
Impact velocity	[m/s]	0.05 2	0.05 3	
Repetition accuracy	[mm]	0.02		
Mounting position		Any		
Product weight	[g]	45	75	110
Ambient temperature [°C]		0 +60		
Corrosion resistance class (	CRC <sup>1)</sup>	2		

1) Corrosion resistance class 2 to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents

Reset time [s]			
Size	5	7	8
Reset time <sup>1)</sup>	≤ 0.2		

1) The specified technical data refers to ambient temperature. At higher temperatures in the 80 °C range, the max. mass and the cushioning work must be reduced by 50% approx. At 0  $^{\circ}\text{C}$  , the reset time may be up to 1 second

Forces [N]			
Size	5	7	8
Min. insertion force <sup>1)</sup>	5	18	80
Max. stop force <sup>2)</sup> in end positions	200	300	500
Min. resetting force <sup>3)</sup>	1.5	2	3.5

- This is the minimum force that must be applied so that the shock absorber is pushed exactly into the retracted end position
   Impact force may not exceed the maximum specified value
   This is maximum force that can be exerted on the piston rod so that the shock absorber advances fully

Energies [J]				
Size	5	7	8	
Max. energy absorption per stroke	1	2	3	
Max. energy absorption per hour	10,000	15,000	21,000	
Max. residual energy	0.01		0.02	

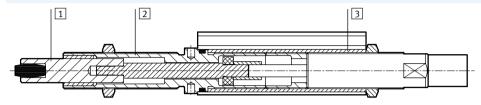
Mass range [kg]			
Size	5	7	8
Permissible mass range up to	2	5	10

## **Stop elements YSRWJ** Technical data



#### Materials

#### Sectional view

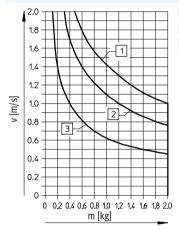


Stop 6	Stop element			
1	Stop bolt	Steel, stainless and reinforced		
2	Distance sleeve	Galvanised steel		
3	Threaded barrel	Brass, nickel-plated		
-	Note on materials	Free of copper, PTFE and silicone		
		Conforms to RoHS		

#### Selection graphs for limit stops with shock absorber YSRWJ

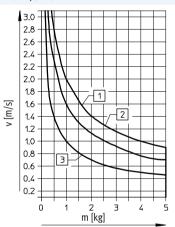
Impact velocity dependent on mass m

#### YSRWJ-5-8-A



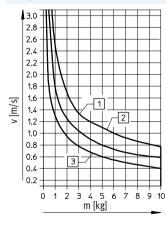
- Without additional force 1
- 2 With additional force A = 50 N
- 3 With additional force A = 100 N

#### YSRWJ-7-10-A



- 1 Without additional force
- 2 With additional force A = 75 N
- 3 With additional force A = 150 N

#### YSRWJ-8-14-A



- Without additional force
- 2 With additional force A = 100 N
- 3 With additional force A = 150 N

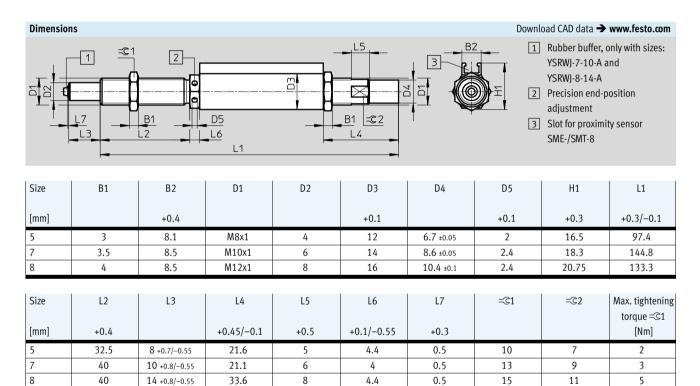
# **Stop elements YSRWJ** Technical data



#### Mode of operation



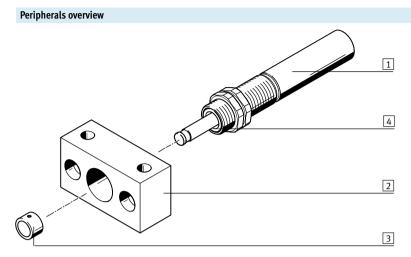
- 1 Soft cushioning characteristics cushioning stroke is adjustable
- 2 End-position sensing via proximity sensor SME-/SMT-8 that can be integrated
- 3 Precision end-position adjustment
- Precision end position thanks to internal, metallic inserts



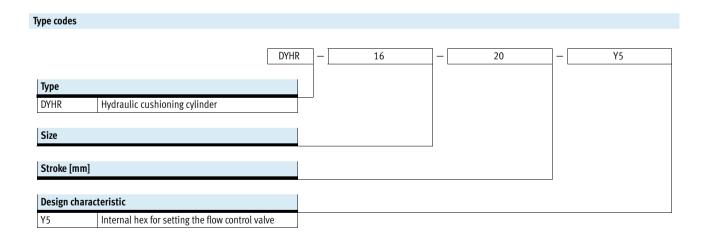
Ordering d	lata	
Size	Part No.	Туре
[mm]		
5	192968	YSRWJ-5-8-A
7	192967	YSRWJ-7-10-A
8	192966	YSRWJ-8-14-A

# **Hydraulic cushioning cylinders DYHR** Peripherals overview and type codes





Access	ories		
	Туре	Brief description	→ Page/Internet
1	Hydraulic cushioning cylinder DYHR	Hydraulic cushioning cylinder with spring return for slow feed speeds	39
2	Mounting flange YSRF	Mounting option for hydraulic cushioning cylinder	42
3	Buffer YSRP	For protecting the piston rod	44
4	Wiper seal; hardened piston rod	The wiper seal (prevents the ingress of dirt) and the hardened piston rod (protects against scratches) greatly increase the service life	_

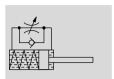


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# Hydraulic cushioning cylinders DYHR Technical data



#### Function





Stroke length 20 ... 60 mm



General technical data								
Size	16	16		20		32		
Stroke	[mm]	20	40	25	50	40	60	
Mode of operation		Hydraulic cus	shioning cylind	der with sprii	ng return			
		Single-acting	, pushing					
Braking speed	Adjustable	Adjustable						
Type of mounting		Via lock nut						
Max. impact velocity	[m/s]	0.3						
Mounting position		Any						
Feed speed	[mm/s]	0.2 100						
Product weight	[g]	190	255	360	440	720	1,380	
Ambient temperature	[°C]	0 +80						
Corrosion resistance class CRC <sup>1)</sup>		1						

<sup>1)</sup> Corrosion resistance class 1 according to Festo standard 940 070 Components subject to low corrosion stress. Transport and storage protection. Parts that do not have primarily decorative surface requirements, e.g. in internal areas that are not visible or behind covers

Reset times [s]					
Size	16	20	25	32	
Short stroke <sup>1)</sup>	≤ 0.4	≤ 0.5	≤ 0.8	≤ 1.2	
Long stroke <sup>1)</sup>	≤ 0.8	≤ 1	-	-	

<sup>1)</sup> Increased reset times must be expected at low temperatures (0 °C). Up to 5 s with sizes 12 and 16 and up to 12 s with sizes 25 and 32.

Forces [N]									
Size	16	20	25	32					
Min. feed force <sup>1)</sup>	160	250	400	640					
Max. feed force <sup>2)</sup>	1,600	2,500	4,000	6,400					
Resetting force <sup>3)</sup>	5.4	9	12.5	18					

- Min. required force for constant braking speed with repetition accuracy
   Corresponds to max. force in the end position
   With piston rod advanced

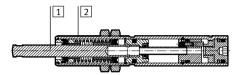
Energies [J]							
Size	16	16			25	32	
Stroke	[mm]	20	40	25	50	40	60
Max. energy absorption per stroke	Max. energy absorption per stroke			62.5	125	160	384
Max. energy absorption per hour	100,000	150,000	135,000	200,000	220,000	330,000	
Max. residual energy in the end po	0.16	•	0.32	•	0.8	2	

# Hydraulic cushioning cylinders DYHR Technical data



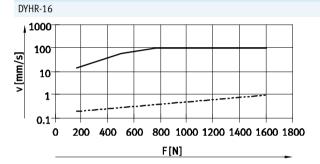
#### Materials

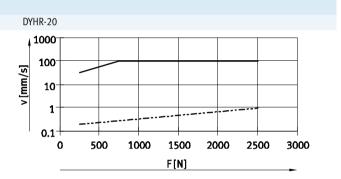
Sectional view

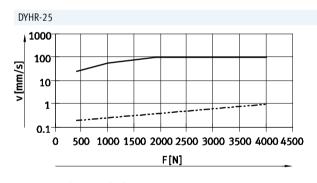


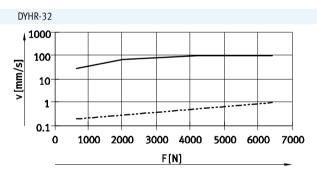
Hydrau	ılic cushioning cylinder						
1 Piston rod Hardened high-alloy steel							
2	Housing	Galvanised steel					
-	Seals	Nitrile rubber					
	Note on materials	RoHS-compliant RoHS-compliant					

### Braking speed v as a function of motive force F and flow control valve setting





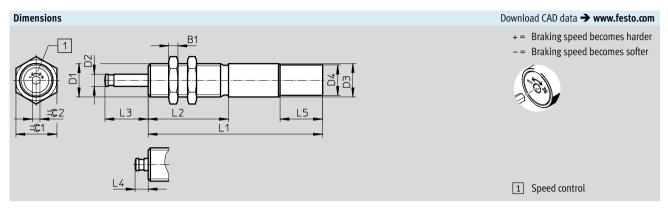




Flow control valve open Flow control valve closed

# Hydraulic cushioning cylinders DYHR Technical data





Size	Stroke [mm]	B1	D1	D2 ∅	D3 Ø +0.15/−0.1	D4 ∅ +0.15	L1
16	20 40	6	M20x1.25	8	20	-	115±0.1 150±0.1
20	25 50	8	M24x1.25	10	24	-	138±0.1 181±0.1
25	40	10	M30x1.5	12	30	28.8	178±0.1
32	60	12	M37x1.5	15	37	34.8	230±0.15

Size	Stroke	L2	L3	L4	L5	=©1	=G2	
	[mm]	±0.1			±0.2			
16	20	53	28.5+0.4/-0.3	9 5 0 454 0 4		24	F	
	40	- 55	48.5+0.4/-0.3	8.5+0.45/-0.4	_	24	)	
20	25	60	35.6+0.4/-0.3	10.6+0.45/-0.4		30	ξ.	
	50	00	60.6+0.4/-0.3	10.0+0.45/-0.4	_	50	,	
25	40	80	52.8+0.4/-0.3	12.8+0.45/-0.4	28	36	6	
32	60	108	76+0.5/-0.4	16+0.5/-0.4	28	46	6	

Ordering	data			
Size	Stroke	Part No.	Туре	
	[mm]			
16	20	1155690	DYHR-16-20-Y5	
	40	1155691	DYHR-16-40-Y5	
20	25	1155692	DYHR-20-25-Y5	
	50	1155693	DYHR-20-50-Y5	
25	40	1155694	DYHR-25-40-Y5	
32	60	1155696	DYHR-32-60-Y5	

## **Accessories for cushioning components**

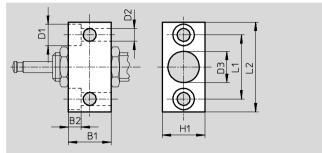
**FESTO** 

Technical data

## Mounting flange YSRF/YSRF-C

Material: Steel





Possible combinations					
Cushioning components Mounting flange	DYSR Y5	Y5-T	YSR-C	YSRW	YDR
YSRF					
YSRF-8	-	-	<b>■</b> 1)	<b>■</b> 1)	-
YSRF-12		-	-	-	-
YSRF-16		_	_	-	
YSRF-20		-	-	-	
YSRF-25		-		-	
YSRF-32		-	•	-	
	·				
YSRF-C					
YSRF-8-C		-			-
YSRF-12-C	-				-
YSRF-16-C	-				-
YSRF-20-C	-				-

<sup>1)</sup> For shock absorber size  $\varnothing$  7

Dimension	s and orde	ring data										
YSRF	SRF											
For size	B1	B2	D1	D2	D3	H1	L1	L2	CRC <sup>1)</sup>	Weight	Part No.	Туре
[mm]										[g]		
8	16	5.5	10	5.5	10.2	16	25	38	2	50	11681	YSRF-8
12	25	6.8	11	6.6	15.2	25	36	50	2	175	11682	YSRF-12
16	30	9	15	9	20.2	30	45	63	2	300	11683	YSRF-16
20	36	11	18	11	24.2	36	56	78	2	535	11684	YSRF-20
25	45	13	20	13.5	30.2	45	63	86	2	895	11685	YSRF-25
32	55	15	24	15.5	37.2	55	80	108	2	1,730	11686	YSRF-32

<sup>1)</sup> Corrosion resistance class 2 according to Festo standard 940 070 Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a surrounding industrial atmosphere or media such as cooling or lubricating agents

YSRF-C												
For size	B1	B2	D1	D2	D3	H1	L1	L2	CRC <sup>1)</sup>	Weight	Part No.	Туре
[mm]										[g]		
8	20	5.5	10	5.5	12.2	20	28	41	2	90	34575	YSRF-8-C
12	25	6.8	11	6.6	16.2	25	36	50	2	180	34576	YSRF-12-C
16	32	9	15	9	22.2	32	45	63	2	330	34577	YSRF-16-C
20	40	11	18	11	26.2	40	56	78	2	700	34578	YSRF-20-C

<sup>1)</sup> Corrosion resistance class 2 according to Festo standard 940 070 Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a surrounding industrial atmosphere or media such as cooling or lubricating agents

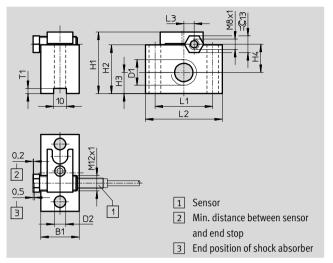
# Accessories for cushioning components Technical data



#### Mounting flange YSRF-S-C

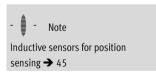
Material: Aluminium, steel Free of copper, PTFE and silicone





Possible combinations	Possible combinations							
Cushioning components	YSR-C	YSRW						
Mounting flange								
YSRF-S-8-C		•						
YSRF-S-12-C								
YSRF-S-16-C		•						
YSRF-S-20-C		•						

Dimension	imensions and ordering data													
For size	B1	D1	D2	H1	H2	Н3	H4	L1	L2	L3	T1	Weight	Part No.	Type
			Ø											
[mm]												[g]		
8	20	M12x1	5.5	35	25	9.5	16	32	45	4	2	12	34579	YSRF-S-8-C
12	25	M16x1	6.6	42	32	12.5	20	36	50	3	4	130	34580	YSRF-S-12-C
16	30	M22x1.5	9	48	38	16.5	22	45	60	8	4	180	34581	YSRF-S-16-C
20	30	M26x1.5	11	52	42	19	23.5	56	80	11.5	4	250	34582	YSRF-S-20-C



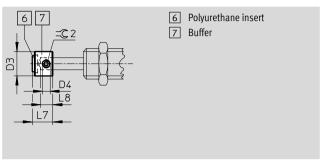
# **Accessories for cushioning components** Technical data



#### Buffer YSRP

Material: Steel, polyurethane





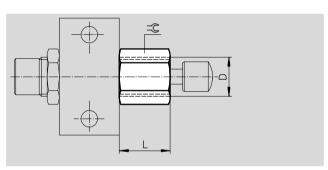
Dimension	imensions and ordering data								
For size [mm]	D3	D4	L7	L8	=© 2	CRC <sup>1)</sup>	Weight [g]	Part No.	Туре
8	8	M2	6,7	4	0,9	2	4	539638	YSRP-8
12	12	M4	10	6	2	2	7	11133	YSRP-12
16	16	M5	13.5	8	2.5	2	15	11134	YSRP-16
20	20	M6	17	10	3	2	27	11135	YSRP-20
25	25	M8	20.5	12	4	2	52	11136	YSRP-25
32	32	M8	26	15	4	2	110	11137	YSRP-32

<sup>1)</sup> Corrosion resistance class 2 according to Festo standard 940 070 Components requiring moderate corrosion resistance. Externally visible parts with primarily decorative surface requirements which are in direct contact with a surrounding industrial atmosphere or media such as cooling or lubricating agents

#### Stop limiter YSRA-C

Material: Steel





Dimension	Dimensions and ordering data									
For size	D	L	=©	Weight	Part No. Type					
[mm]				[g]						
7	M10x1	14.5	13	12	150932 YSRA-7-C					
8	M12x1	18	15	28	150933 YSRA-8-C					
12	M16x1	24.5	19	48	150934 YSRA-12-C					

# Accessories for cushioning components Technical data



#### Reducing sleeve DAYH

Material: Stainless steel



To improve the cushioning performance in the case of underload, the built-in shock absorber can be replaced by the next smallest shock absorber with the help of the reducing sleeve.

Built-in shock absorber	Part No.	Reducing sleeve	Part No.	Next smallest shock absorber
YSRC	l.		l.	
YSR-5-5-C	1165476	DAYH-4	540060	YSR-4-4-C
DYSC				
DYSC-8-8-Y1F	1165484	DAYH-7	548012	DYSC-7-5-Y1F
DYSC-7-5-Y1F	1165480	DAYH-5	548011	DYSC-5-5-Y1F
DYSW				
DYSW-12-20-Y1F	1165491	DAYH-10	548074	DYSW-10-17-Y1F
DYSW-10-17-Y1F	1165488	DAYH-8	548073	DYSW-8-14-Y1F
DYSW-8-14-Y1F	1165484	DAYH-7	548072	DYSW-7-10-Y1F
DYSW-7-10-Y1F	1165480	DAYH-5	548071	DYSW-5-8-Y1F
DYSW-5-8-Y1F	1165476	DAYH-4	548070	DYSW-4-6-Y1F

Ordering data	- Proximity sensors for T-slot, magneto-r	esistive				Technical data → Internet: smt
	Type of mounting	Switch	Electrical connection	Cable length	Part No.	Туре
		output		[m]		
N/O contact						
~	Insertable in the slot from above, flush	PNP	Cable, 3-wire	2.5	574335	SMT-8M-A-PS-24V-E-2,5-0E
THE STATE OF THE S	with cylinder profile, short design		Plug M8x1, 3-pin	0.3	574334	SMT-8M-A-PS-24V-E-0,3-M8D
4			Plug M12x1, 3-pin	0.3	574337	SMT-8M-A-PS-24V-E-0,3-M12
		NPN	Cable, 3-wire	2.5	574338	SMT-8M-A-NS-24V-E-2,5-OE
			Plug M8x1, 3-pin	0.3	574339	SMT-8M-A-NS-24V-E-0,3-M8D
N/C contact						
~	Insertable in the slot from above, flush	PNP	Cable, 3-wire	7.5	574340	SMT-8M-A-PO-24V-E-7,5-OE
THE WAY	with cylinder profile, short design					
Ψ						

Ordering data	- Proximity sensors for T-slot, magnetic i	eed				Technical data → Internet: sme
	Type of mounting	Switch	Electrical connection	Cable length	Part No.	Туре
		output		[m]		
N/O contact						
	Insertable in the slot from above, flush	Contacting	Cable, 3-wire	2.5	543862	SME-8M-DS-24V-K-2,5-OE
T. S.	with cylinder profile		Plug M8x1, 3-pin	0.3	543861	SME-8M-DS-24V-K-0,3-M8D
	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	2.5	150855	SME-8-K-LED-24
	with the cylinder profile		Plug M8x1, 3-pin	0.3	150857	SME-8-S-LED-24
N/C contact						
	Insertable in the slot lengthwise, flush	Contacting	Cable, 3-wire	7.5	160251	SME-8-O-K-LED-24
	with the cylinder profile					

# Accessories for cushioning components Technical data



Ordering data	a – Inductive sensors	M8, for mounting flange	YSRF-S-C				Technical data → Internet: sien
	Electrical connection	on	Switch	LED	Cable length	Part No.	Туре
	Cable	M8 plug	output		[m]		
NO contact							
	3 wires	-	PNP		2.5	150386	SIEN-M8B-PS-K-L
	-	3-pin	PNP	•	-	150387	SIEN-M8B-PS-S-L
NC contact							
	3 wires	-	PNP		2.5	150390	SIEN-M8B-PO-K-L
	_	3-pin	PNP	•	-	150391	SIEN-M8B-PO-S-L

Ordering data	- Connecting cables				Technical data → Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
			5	541334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
			5	541341	NEBU-M8W3-K-5-LE3

### Calculation tool for cushioning components

Technical data

This selection aid helps you find the right shock absorber for every application.

When you are choosing a shock absorber, we recommend that you proceed as follows:

When you are choosing a shock exceeded:

absorber for your application, ensure that the following values are not

The (angular) velocity required in the formulae is the velocity at the time of the impact on the shock absorber. This depends on the dynamic

It is better to determine the mean velocity ( $v_m = s/t$  or  $\omega_m = \varphi/t$ ).

The following formulae are required for the calculation:

The following applies additionally for rotary motions:

The following abbreviations are used:

= Additional force = F + G [N]

 $A = \frac{M}{R} + m \times g \times \sin \alpha \times \frac{a}{R}$ 

= Cylinder force minus frictional force [N]

= Force due to weight = m x g x sin  $\alpha$ 

Special cases:

= 0°: Horizontal motion G = 0

= 90°: Downward motion

= 90°: Upward motion:  $G = -m \times g$ 

2. Select a shock absorber from the graphs on the following pages.

3. Check your selection on the basis of its maximum cushioning energy (W<sub>max.</sub>)

Max. energy absorption per hour

Max. residual energy

Max. stop force in end position

The fact that the (angular) velocity appears in the calculation as a squared value means that the expected error becomes considerably larger. The calculation can thus be regarded only as an approximation. The safety factor does, however,

ensure that the selected shock

absorber is not too small.

Note

Sizing software Shock absorber selection

**FESTO** 

→www.festo.com

characteristics of the drive component and is thus difficult to determine.

drive concerned, calculations should in the interests of safety be based on the following values: = 1.25 ... 2 v<sub>m</sub>

In order to prevent damage to the

1. Determine the following values,

- Equivalent mass m<sub>equiv</sub>

Permissible energy load per

= 25%

= 100% Recommended energy load per

= 50% ... 100 %

- Impact velocity (v)

- Force (A)

stroke:

W<sub>min</sub>.

W<sub>max</sub>.

stroke:

Wopt.

effective at the time of impact:

 $\omega = 1.25 ... 2 \omega_{m}$ Guide values for linear motions: Factor 2 with strokes < 50 mm. factor 1.5 with strokes > 50 mm and ر 100 mm.

factor 1.25 with strokes > 100 mm.

A = F + G

 $m_{equiv.} = \frac{J}{R^2}$ 

 $A = F + m \times g \times \sin \alpha$ 

 $W_{total} = \frac{1}{2} \times m \times v^2 + A \times s < W_{max.}$ 

 $W_h = W_{total} \times Stroke \div Hours < W_{hmax}$ 

v = Impact velocity [m/s]

m<sub>equiv.</sub>= Equivalent mass [kg]

= Acceleration due to gravity  $9.81 \, [m/s^2]$ 

= Shock absorber stroke [m]

 $\alpha$  = Impact angle [°]

Wtotal = Cushioning work/stroke [J]

W<sub>h</sub> = Cushioning work/hour [J]

= Mass moment of inertia  $[kg \times m^2]$ 

= Distance between mass pivot point and shock absorber [m]

= Angular velocity [rad/s]

= Drive torque [Nm]

= Distance between centre of gravity of mass and pivot point

47

### **Calculation tool for cushioning components**

**FESTO** 

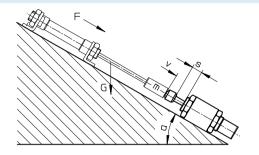
Technical data

#### Sizing example for linear motion

This example illustrates the procedure for the selection of a shock absorber for the application shown in the adjacent drawing:

A = F + m x g x sin 
$$\alpha$$
  
= 190 N + 50 x 9.81 x sin  $\alpha$  N  
= 537 N

 $m_{equiv} = m = 50 \text{ kg}$ 



= 50 kg = 1.5 m/s

 $\alpha = 45^{\circ}$ 

F = 190 N

( $\varnothing$  20 mm with p = 6 bar, 1,800 strokes per hour)

In the process of selecting shock absorbers on the basis of the graphs (see data sheets), the force (A) is governed by the first curve to the right of the point of intersection of the equivalent mass (mequiv) and the impact velocity (v). The curves move to the left as the additional force increases.

Three force curves are given for each shock absorber. Interim values must be calculated by averaging. As the

graphs show (continuous line), possible choices are the shock absorbers DYSR-25-40 and YSR-25-40-C. We must now determine whether the maximum permissible values for cushioning work (W<sub>max.</sub>) and cushioning work per hour (W<sub>hmax.</sub>) are not being exceeded. These maximum permissible values and the stroke length (s) can be found in the tables (below the graphs).

Experiment:

 $\begin{aligned} W_{total} &= \frac{1}{2} \, x \, m \, x \, v^2 + A \, x \, s \\ &= (1/2 \, x \, 50 \, x \, 1.5^2 \, + \\ &= 537 \, x \, 0.04) \, Nm = 78 \, J \end{aligned}$ 

W<sub>h</sub> = W<sub>total</sub> x strokes/h = 78 Nm x 1,800 = 140,000 J For the above application, both shock absorbers are suitable.
Further selection criteria are adjustment facilities and size.

Result		
	DYSR-25-40	YSR-25-40-C
W <sub>total</sub>	78 J	78 J
$W_h$	140,000 J	140,000 J
W <sub>max</sub> . <sup>1)</sup>	160 J > W <sub>total</sub>	160 J > W <sub>total</sub>
W <sub>hmax</sub> .	220,000 > W <sub>max</sub> .	150,000 > W <sub>max</sub> .

<sup>1)</sup> The degree of utilisation is 49% in both cases.

### **Calculation tool for cushioning components**

**FESTO** 

Technical data

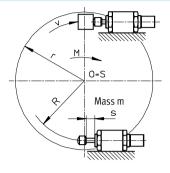
#### Sizing example for rotary motion

Example for rotary motion:

$$m_{equiv} = J/R^2 = 8 \text{ kg}$$

$$v = \omega \times R$$

$$A = M/R = 40 N$$



 $J = 2 \text{ kg m}^2$ 

 $\omega = 4 \text{ rad/s}$ 

R = 0.5 m

M = 20 Nm

900 strokes per hour

In the process of selecting shock absorbers on the basis of graphs (see data sheets), the force (A) is governed by the first curve to the right of the point of intersection of the equivalent mass  $(m_{\text{equiv}})$  and the impact velocity (v). The curves move to the left as the additional force increases.

Three force curves are given for each shock absorber. Interim values must be calculated by averaging. As the graphs show (dotted line), possible choices are the shock absorbers DYSR-16-20 and YSR-16-20-C.

We must now determine whether the maximum permissible values for cushioning work (W<sub>max.</sub>) and cushioning work per hour (W<sub>hmax.</sub>) are not being exceeded. These maximum permissible values and the stroke length (s) can be found in the tables (below the graphs).

Note: The impact angle must be noted with rotary applications.

$$tan\,\alpha\,=\,\frac{s}{R}$$

s = Cushioning stroke

Experiment:

$$W_{total} = \frac{1}{2} \times m \times v^2 + A \times s$$
$$= (1/2 \times 8 \times 2^2 + 40 \times 0.02) J = 17 J$$

$$W_h = W_{total} x strokes/h$$

For the above application, both shock absorbers are suitable.
Further selection criteria are adjustment facilities and size.

Result		
	DYSR-16-20 <sup>3)</sup>	YSR-16-20-C
W <sub>total</sub>	17 J	17 J
$W_h$	15,300 J	15,300 J
W <sub>max</sub> .	32 J > W <sub>total</sub> <sup>1)</sup>	30 J > W <sub>total</sub> <sup>2)</sup>
W <sub>hmax</sub> .	$100,000 > W_{max}$ .	64,000 > W <sub>max</sub> .

- 1) The degree of utilisation is 53%.
- The degree of utilisation is 57%.
- 3) Use without buffer.